IAI
Quality and Innovation

PMEC
AMEC

3-POSITION CONTROLLER FOR ROBO CYLINDER

www.intelligentactuator.com

3-position Controller for ROBO Cylinders

Mechanical Engineer Control (MEC) **MEC**

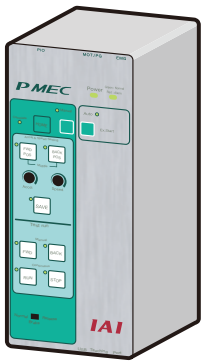
Affordable and Easy to Use

The MEC allows users, including mechanical engineers, to easily operate IAI's ROBO Cylinders, which are highly recognized in the FA industry for their wide selection of models and superior performance. Just by plugging in the power and setting the speed and acceleration, you can start using the MEC just like an air cylinder, by inputting the Forward and Back signals from the PLC.

1. Affordable

The PMEC comes complete with a controller, power supply, acceleration and speed change functions, and all necessary features including a PC connection cable, all at an affordable price.

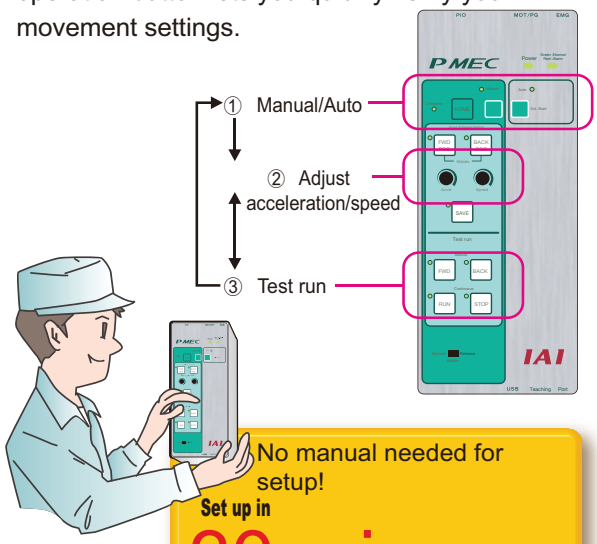
The price of the MEC and a slider-type ROBO Cylinder combined is comparable to the total cost of a rodless air cylinder, electromagnetic valve, auto switch, and speed controller.



Complete with a controller, power supply, PC connection cable, and all other necessary features such as acceleration and speed change functions, all at an affordable price

2. Easy to Use

Just set the desired speed and acceleration using the knobs on the control panel. The continuous operation button lets you quickly verify your movement settings.

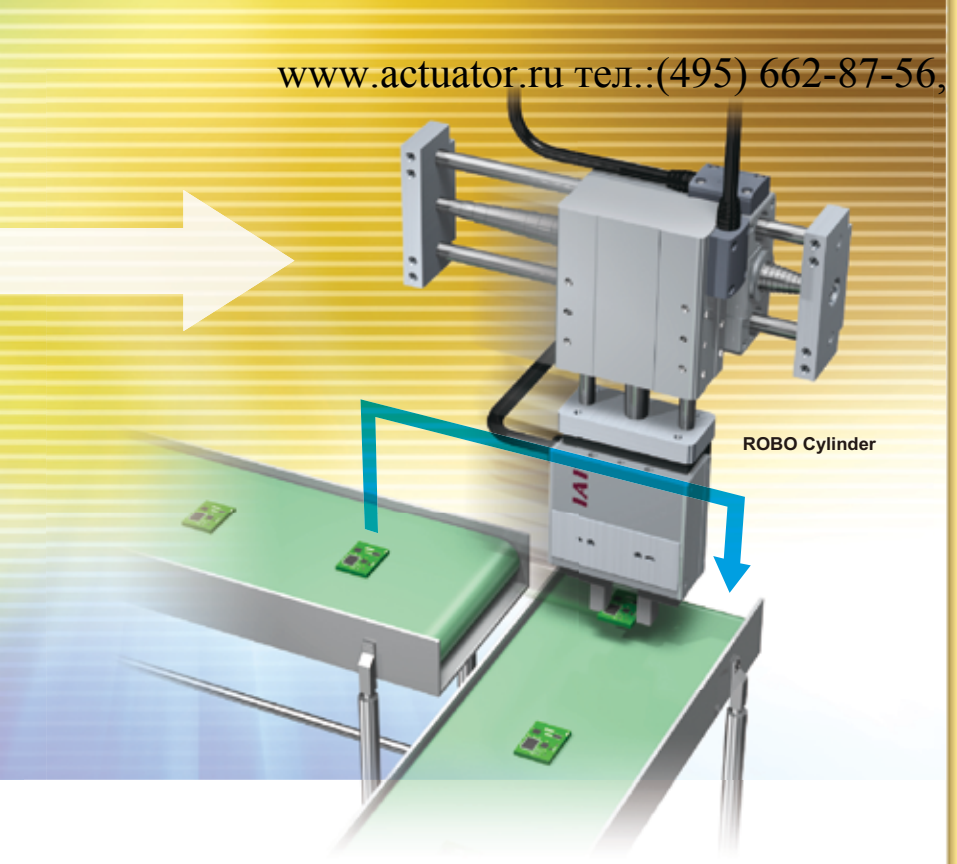


No manual needed for setup!

Set up in

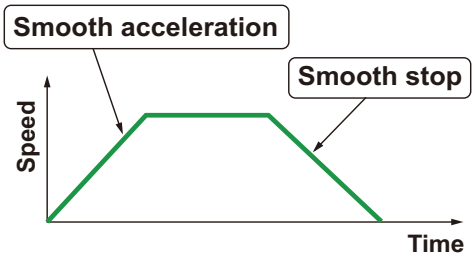
30 min

after opening.



3. Versatile

- You can set the speed and acceleration/deceleration to any value within the specifications of each actuator.
- You can control not only 2-position stops, but also 3-position stops when you use the optional MEC-dedicated PC software. In addition, you can set any start and end positions within the stroke.

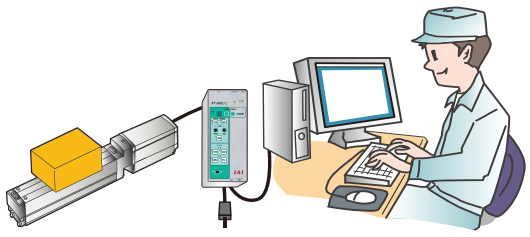


Boosts your productivity with features you can only see in electric cylinders

Highly Functional

Other Features of MEC/ROBO Cylinders

- **Energy saving**
  Only one-fifth of the power consumption of air cylinders (calculated by IAI).
- **Stable operation even at low speeds**
- **Supports press operation**

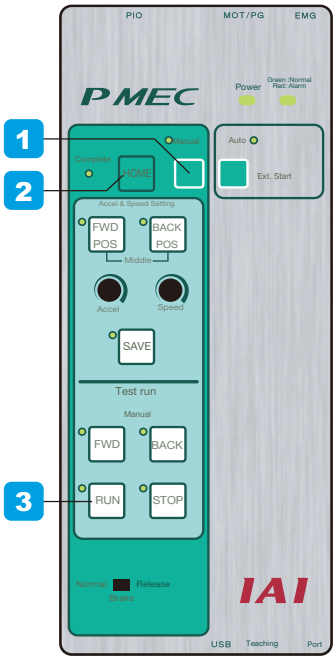


Anyone can set up and use the MEC, even without any electrical knowledge.

1 Connect the wiring (see page 17).

2 Turn the power on.

3 Verify proper operation.

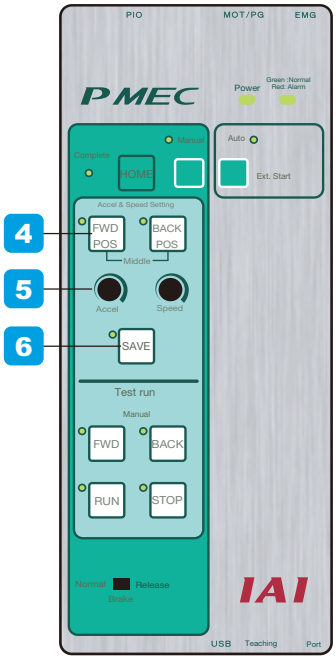


1. Press and hold the MANUAL button for at least 1 second.
2. Press the HOME button to prepare for operation.
   (The Complete LED turns on when the home is complete.)
3. Check for safety and press the RUN button for a test run.

With just these steps, the operation (Continuous Operation) starts.

4 To change settings:

Follow the steps below to change the acceleration and speed settings.
You can do these steps even during continuous test operation.



4. Press the FWD POS or BACKPOS button to select which movement to change.
5. Turn the ACCEL and SPEED knobs to the desired values.
6. The new settings are applied by pressing the SAVE button.
   (If the MEC is in continuous operation, the new values will take effect on the next operation.)

Use the MEC-dedicated PC software to change the start/end positions, configure intermediate stop settings, or to execute a press operation.

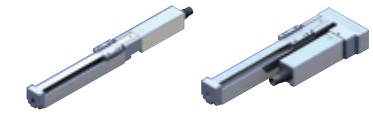
*Please contact IAI for more information.

A versatile lineup of ROBO Cylinders, ranging from mini models similar to air cylinders, to rotary and gripper types.

Actuators Supported by PMEC

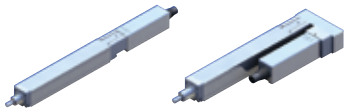
Mini ROBO Cylinders

RCP3 Mini Slider Type



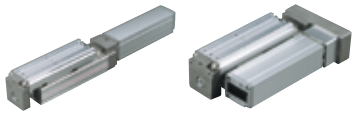
Motor Unit Coupling Type | Motor Reversing Type

RCP3 Mini Rod Type



Motor Unit Coupling Type | Motor Reversing Type

RCP3 Mini Table Type



Motor Unit Coupling Type | Motor Reversing Type

ROBO Cylinder

RCP3 Series

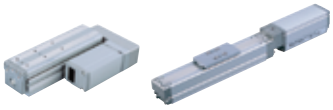
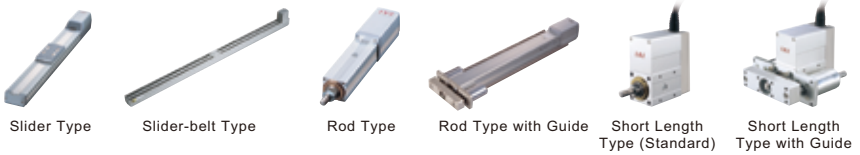


Table Type | Slider Type

A pulse motor type that combines high-function and low price



Slider Type | Slider-belt Type | Rod Type | Rod Type with Guide | Short Length Type (Standard) | Short Length Type with Guide

Rotary Type | Gripper Type | Small Gripper | 3-Finger Gripper

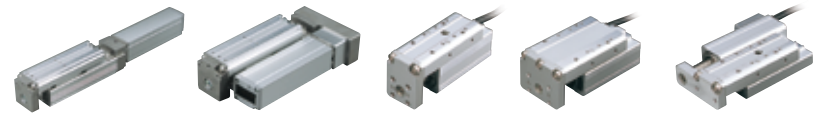
Actuators Supported by AMEC

Mini ROBO Cylinders

RCA2 Mini Rod Type

Short Length Fixed Nut Type | Short Length Tapped Hole Type | Short Length Single Guide Free Mount Type | Short Length Double Guide Free Mount Type | Short Length Double Guide Slide Unit Type

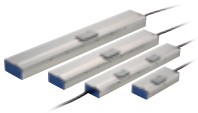
RCA2 Mini Table Type



Motor Unit Coupling Type | Motor Reversing Type | Short Length Compact Type | Short Length Wide Type | Short Length Flat Type

RCL Mini Linear Servo Type

Micro Slider Slim Type



Micro Slider Long Stroke Type

Micro Cylinder

ROBO Cylinders

RCA Series: Servo-type actuators operable at 24V

Coupling Type | Motor Reversing Type | Rod Type with Guide | Slider Type | Motor Reversing Type

RCA2 Series

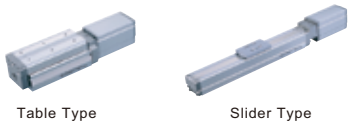
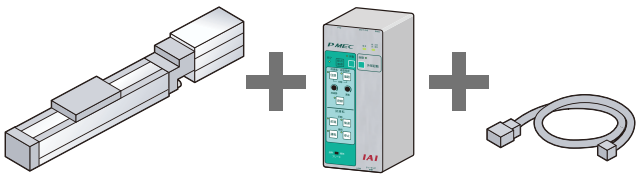


Table Type | Slider Type

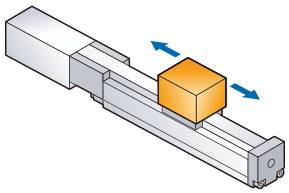
ROBO Cylinder MEC Kits

What are ROBO Cylinder MEC Kits?

Available for slider and rod types of electric actuators, the ROBO cylinder MEC kit is a set of IAI's most recommended equipment that meets specific speed and load capacity requirements. The MEC kit is a good option if you are not sure which model to choose from the wide range of selections. There are many other types of ROBO Cylinders besides those that are available in the MEC kit. For details, refer to the ROBO Cylinder General Catalog.



Actuator　　Controller Type　　Cable

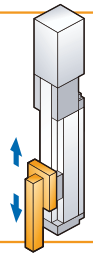


MEC Slider Kit (Horizontal Type)

This kit is suitable for horizontal transport and positioning of the workpieces.

pattern A　Horizontal Load Capacity Less than 5 kg

Low speed	Medium speed	High speed
100mm/s	200mm/s	400mm/s

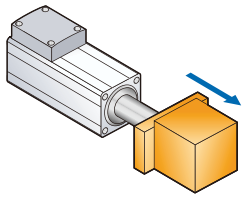


MEC Slider Kit (Vertical Type)

This kit is suitable for vertical transport and positioning of the workpieces.

pattern D　Vertical load capacity Less than 1 kg

Low speed	Medium speed	High speed
50mm/s	100mm/s	250mm/s

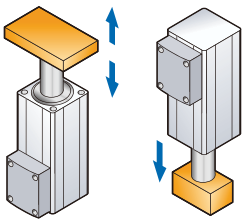


MEC Rod Kit (Horizontal Type)

This kit is suitable for clamping and pushing the workpieces.

pattern A　Horizontal Load Capacity Less than 10 kg

Low speed	Medium speed	High speed
100mm/s	300mm/s	400mm/s

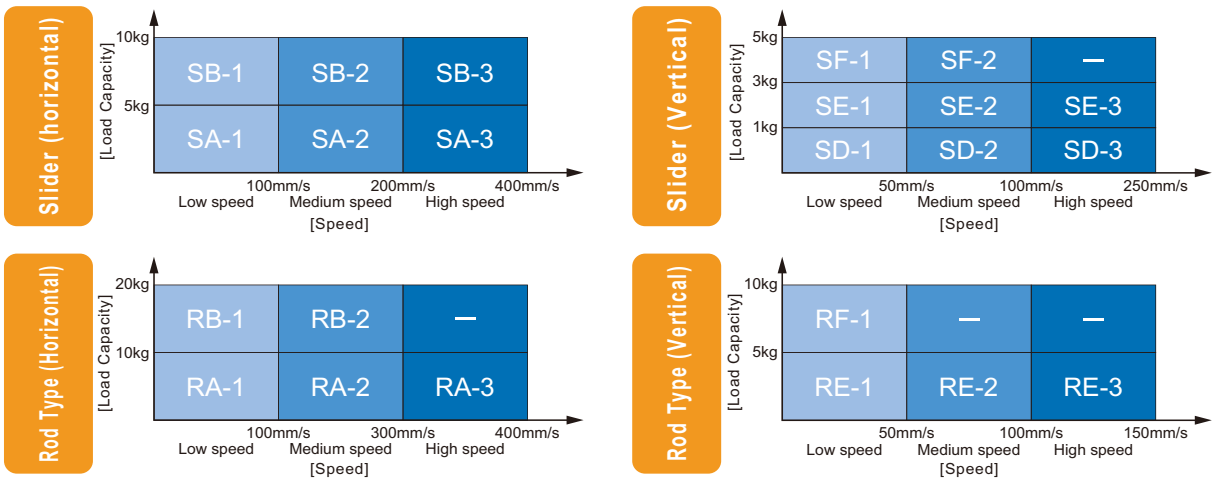


MEC Rod Kit (Vertical Type)

This kit is suitable for raising/lowering the workpieces and stackers, or for press-fitting and caulking the workpieces.

pattern E　Vertical load capacity Less than 5 kg

Low speed	Medium speed	High speed
50mm/s	100mm/s	150mm/s



pattern B Horizontal Load Capacity **Less than 10 kg**

Low speed	Medium speed	High speed
100mm/s	200mm/s	400mm/s

P7

pattern E Vertical load capacity **Less than 3 kg**

Low speed	Medium speed	High speed
50mm/s	100mm/s	250mm/s

pattern F Vertical load capacity **Less than 5 kg**

Low speed	Medium speed
50mm/s	100mm/s

P9

pattern B Horizontal Load Capacity **Less than 20 kg**

Low speed	Medium speed
100mm/s	300mm/s

P11

pattern F Vertical load capacity **Less than 10 kg**

Low speed
50mm/s

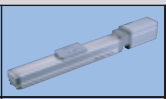
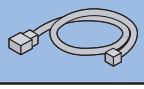
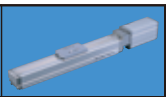
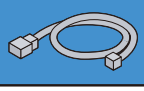
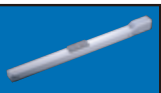
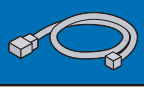
P13

ROBO Cylinder MEC Kits

Selection procedure **Select the MEC kit that is right for you.**

1. Select pattern A if each workpiece transported weighs less than 5kg, or pattern B if less than 10kg.
2. Once you have decided on the pattern, select the kit according to the desired speed and stroke.
3. Place your order by the kit number.

pattern A Horizontal load capacity Less than 5kg

Speed	Kit Configuration			Stroke	Kit Number
Low Speed (100mm/sec)	Actuator		RCP3-SA4C-I-35P -10-①-P3-M →P24	50mm	SA-1-050
				100mm	SA-1-100
				150mm	SA-1-150
				200mm	SA-1-200
				250mm	SA-1-250
				300mm	SA-1-300
				350mm	SA-1-350
				400mm	SA-1-400
				450mm	SA-1-450
				500mm	SA-1-500
	Controller Type		PMEC-C-35PI-NP-2-1		
	Cable		5m cable included		
Medium Speed (200mm/sec)	Actuator		RCP3-SA4C-I-35P -10-①-P3-M →P24	50mm	SA-2-050
				100mm	SA-2-100
				150mm	SA-2-150
				200mm	SA-2-200
				250mm	SA-2-250
				300mm	SA-2-300
				350mm	SA-2-350
				400mm	SA-2-400
				450mm	SA-2-450
				500mm	SA-2-500
	Controller Type		PMEC-C-35PI-NP-2-1		
	Cable		5m cable included		
High Speed* (400 mm/sec)	Actuator		RCP2-SA5C-I-42P -12-①-P3-M →P26	50mm	SA-3-050
				100mm	SA-3-100
				150mm	SA-3-150
				200mm	SA-3-200
				250mm	SA-3-250
				300mm	SA-3-300
				350mm	SA-3-350
				400mm	SA-3-400
				450mm	SA-3-450
				500mm	SA-3-500
				550mm	SA-3-550
				600mm	SA-3-600
				650mm	SA-3-650
				700mm	SA-3-700
				750mm	SA-3-750
				800mm	SA-3-800
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		

* This speed cannot be attained if the stroke is 750 mm or more.

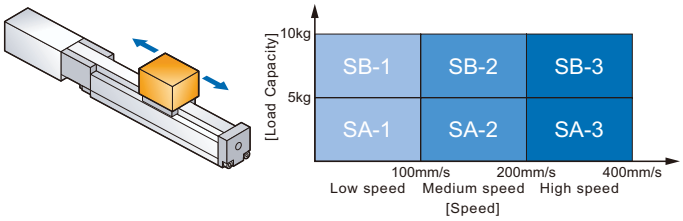
① A placeholder for the value of the desired stroke.

Example: "50" for 50mm

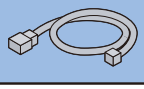
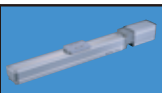
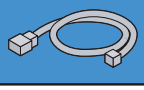
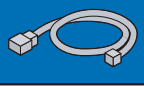
MEC Slider Kit (Horizontal Type)

Ordering Example:

If load capacity = 5kg, speed = medium speed (200mm/sec), and stroke = 300mm, the kit number to order is **SA-2-300**.



pattern B Horizontal load capacity Less than 10kg

Speed			Kit Configuration	Stroke	Kit Number
Low Speed (100mm/sec)	Actuator		RCP3-SA5C-I-42P -6-①-P3-M →P25	50mm	SB-1-050
				100mm	SB-1-100
				150mm	SB-1-150
				200mm	SB-1-200
				250mm	SB-1-250
				300mm	SB-1-300
				350mm	SB-1-350
				400mm	SB-1-400
				450mm	SB-1-450
				500mm	SB-1-500
				550mm	SB-1-550
				600mm	SB-1-600
				650mm	SB-1-650
				700mm	SB-1-700
				750mm	SB-1-750
				800mm	SB-1-800
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
Medium Speed* (200mm/sec)	Actuator		RCP3-SA5C-I-42P -6-①-P3-M →P25	50mm	SB-2-050
				100mm	SB-2-100
				150mm	SB-2-150
				200mm	SB-2-200
				250mm	SB-2-250
				300mm	SB-2-300
				350mm	SB-2-350
				400mm	SB-2-400
				450mm	SB-2-450
				500mm	SB-2-500
				550mm	SB-2-550
				600mm	SB-2-600
				650mm	SB-2-650
				700mm	SB-2-700
				750mm	SB-2-750
				800mm	SB-2-800
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
High Speed* (400 mm/sec)	Actuator		RCP2-SA7C-I-56P -16-①-P3-M →P27	50mm	SB-3-050
				100mm	SB-3-100
				150mm	SB-3-150
				200mm	SB-3-200
				250mm	SB-3-250
				300mm	SB-3-300
				350mm	SB-3-350
				400mm	SB-3-400
				450mm	SB-3-450
				500mm	SB-3-500
				550mm	SB-3-550
				600mm	SB-3-600
				650mm	SB-3-650
				700mm	SB-3-700
				750mm	SB-3-750
				800mm	SB-3-800
	Controller Type		PMEC-C-56PI-NP-2-1		
	Cable		5m cable included		

* This speed cannot be attained if the stroke is 700 mm or more.

ROBO Cylinder MEC Kits

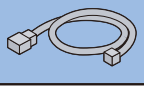
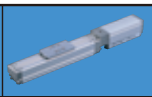
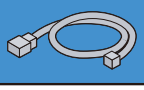
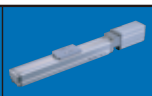
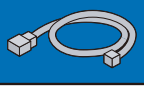
Selection procedure **Select the MEC kits that is right for you.**

❶ Select pattern D if each workpiece transported weighs less than 1kg, pattern E if less than 3kg, or pattern F if less than 5kg.

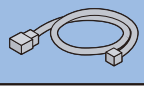
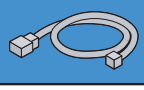
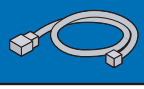
❷ Once you have decided on the pattern, select the kit according to the desired speed and stroke.

❸ Place your order by the kit number.

pattern D Vertical Load Capacity Less than 1kg

Speed	Kit Configuration		Stroke	Kit Number
Low Speed (50mm/sec)	Actuator	 RCP3-SA3C-I-28P-4-① -P3-M-B →P23	50mm	SD-1-050
			100mm	SD-1-100
			150mm	SD-1-150
			200mm	SD-1-200
			250mm	SD-1-250
			300mm	SD-1-300
	Controller Type	 PMEC-C-28PI-NP-2-1		
	Cable	 5m cable included		
Medium Speed (100mm/sec)	Actuator	 RCP3-SA3C-I-28P-4-① -P3-M-B →P23	50mm	SD-2-050
			100mm	SD-2-100
			150mm	SD-2-150
			200mm	SD-2-200
			250mm	SD-2-250
			300mm	SD-2-300
	Controller Type	 PMEC-C-28PI-NP-2-1		
	Cable	 5m cable included		
High Speed (250mm/sec)	Actuator	 RCP3-SA4C-I-35P-5-①-P3-M-B →P24	50mm	SD-3-050
			100mm	SD-3-100
			150mm	SD-3-150
			200mm	SD-3-200
			250mm	SD-3-250
			300mm	SD-3-300
			350mm	SD-3-350
			400mm	SD-3-400
			450mm	SD-3-450
			500mm	SD-3-500
	Controller Type	 PMEC-C-35PI-NP-2-1		
	Cable	 5m cable included		

pattern E Vertical Load Capacity Less than 3kg

Speed	Kit Configuration	
Low Speed (50mm/sec)	Actuator	 RCP3-SA4C-I-35P-5-①-P3-M-B →P24
	Controller Type	 PMEC-C-35PI-NP-2-1
	Cable	 5m cable included
Medium Speed (100mm/sec)	Actuator	 RCP3-SA4C-I-35P-5-①-P3-M-B →P24
	Controller Type	 PMEC-C-35PI-NP-2-1
	Cable	 5m cable included
High Speed* (250 mm/sec)	Actuator	 RCP2-SA5C-I-42P-6-① -P3-M-BL →P26
	Controller Type	 PMEC-C-42PI-NP-2-1
	Cable	 5m cable included

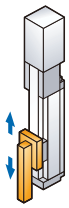
* This speed cannot be attained if the stroke is 650 mm or more.

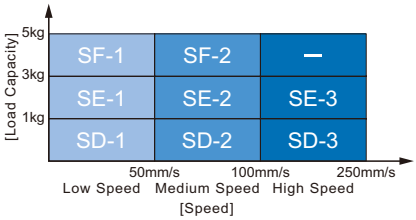
①A placeholder for the value of the desired stroke.
Example: "50" for 50mm

MEC Slider Kit (Vertical Type)

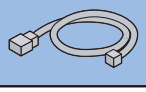
Ordering Example:

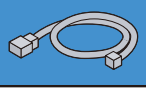
If load capacity = less than 3kg, speed = low speed (50mm/sec), and stroke = 100mm, the bundle package to order is **SE-1-100**.





pattern F — Vertical Load Capacity Less than 5kg

Speed	Kit Configuration			Stroke	Kit Number
Low Speed (50mm/sec)	Actuator		RCP3-SA5C-I-42P -3-① -P3-M-B →P25	50mm	SF-1-050
				100mm	SF-1-100
				150mm	SF-1-150
				200mm	SF-1-200
				250mm	SF-1-250
				300mm	SF-1-300
				350mm	SF-1-350
				400mm	SF-1-400
				450mm	SF-1-450
				500mm	SF-1-500
	Controller Type		PMEC-C-42PI-NP-2-1	550mm	SF-1-550
				600mm	SF-1-600
				650mm	SF-1-650
				700mm	SF-1-700
				750mm	SF-1-750
				800mm	SF-1-800
	Cable		5m cable included		

Speed	Kit Configuration			Stroke	Kit Number
Medium Speed * (100mm/sec)	Actuator		RCP3-SA5C-I-42P -3-① -P3-M-B →P25	50mm	SF-2-050
				100mm	SF-2-100
				150mm	SF-2-150
				200mm	SF-2-200
				250mm	SF-2-250
				300mm	SF-2-300
				350mm	SF-2-350
				400mm	SF-2-400
				450mm	SF-2-450
				500mm	SF-2-500
	Controller Type		PMEC-C-42PI-NP-2-1	550mm	SF-2-550
				600mm	SF-2-600
				650mm	SF-2-650
				700mm	SF-2-700
				750mm	SF-2-750
				800mm	SF-2-800
	Cable		5m cable included		

* This speed cannot be attained if the stroke is 750 mm or more.

Stroke	Kit Number
50mm	SE-1-050
100mm	SE-1-100
150mm	SE-1-150
200mm	SE-1-200
250mm	SE-1-250
300mm	SE-1-300
350mm	SE-1-350
400mm	SE-1-400
450mm	SE-1-450
500mm	SE-1-500

50mm	SE-2-050
100mm	SE-2-100
150mm	SE-2-150
200mm	SE-2-200
250mm	SE-2-250
300mm	SE-2-300
350mm	SE-2-350
400mm	SE-2-400
450mm	SE-2-450
500mm	SE-2-500

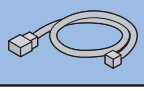
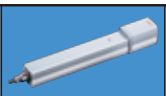
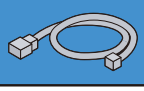
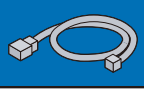
50mm	SE-3-050
100mm	SE-3-100
150mm	SE-3-150
200mm	SE-3-200
250mm	SE-3-250
300mm	SE-3-300
350mm	SE-3-350
400mm	SE-3-400
450mm	SE-3-450
500mm	SE-3-500
550mm	SE-3-550
600mm	SE-3-600
650mm	SE-3-650
700mm	SE-3-700
750mm	SE-3-750
800mm	SA-3-800

ROBO Cylinder MEC Kits

Selection procedure **Select the MEC kit that is right for you.**

1. Select pattern A if each workpiece transported weighs less than 10kg, or pattern B if less than 20kg.
2. Once you have decided on the pattern, select the kit according to the desired speed and stroke.
3. Place your order by the kit number.

pattern A Horizontal Load Capacity Less than 10 kg

Speed	Kit Configuration			Stroke	Kit Number
Low Speed* (100mm/sec)	Actuator		RCP2-RA4C-I-42P -2.5-①-P3-M →P28	50mm	RA-1-050
				100mm	RA-1-100
				150mm	RA-1-150
				200mm	RA-1-200
				250mm	RA-1-250
				300mm	RA-1-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
Medium Speed (300mm/sec)	Actuator		RCP2-RA4C-I-42P -10-①-P3-M →P28	50mm	RA-2-050
				100mm	RA-2-100
				150mm	RA-2-150
				200mm	RA-2-200
				250mm	RA-2-250
				300mm	RA-2-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
High Speed* (400mm/sec)	Actuator		RCP2-RA4C-I-42P -10-①-P3-M →P28	50mm	RA-3-050
				100mm	RA-3-100
				150mm	RA-3-150
				200mm	RA-3-200
				250mm	RA-3-250
				300mm	RA-3-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		

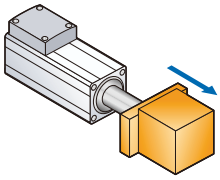
* This speed cannot be attained if the stroke is 300mm or more.

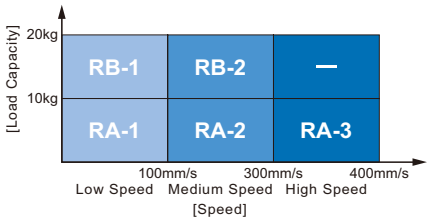
① A placeholder for the value of the desired stroke.
Example: "50" for 50mm

MEC Rod Kit (Horizontal Type)

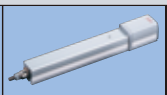
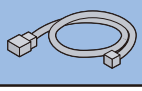
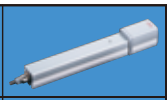
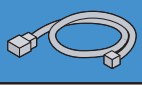
Ordering Example:

If load capacity = less than 10kg, speed = high speed (400mm/sec), and stroke = 150mm, the bundle package number to order is **RA-3-150**.





pattern B Horizontal Load Capacity Less than 20 kg

Speed	Kit Configuration			Stroke	Kit Number
Low Speed* (100mm/sec)	Actuator		RCP2-RA4C-I-42P -2.5-①-P3-M →P28	50mm	RB-1-050
				100mm	RB-1-100
				150mm	RB-1-150
				200mm	RB-1-200
				250mm	RB-1-250
				300mm	RB-1-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
Medium Speed (300mm/sec)	Actuator		RCP2-RA4C-I-42P -10-①-P3-M →P28	50mm	RB-2-050
				100mm	RB-2-100
				150mm	RB-2-150
				200mm	RB-2-200
				250mm	RB-2-250
				300mm	RB-2-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		

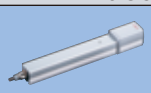
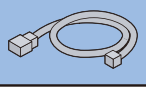
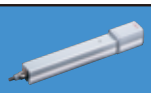
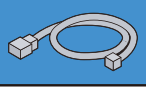
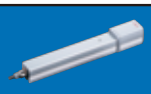
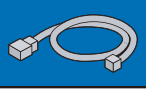
* This speed cannot be attained if the stroke is 300mm or more.

ROBO Cylinder MEC Kits

Selection procedure **Select the MEC kit that is right for you.**

1. Select pattern E if each workpiece transported weighs less than 5kg, or pattern F if less than 10kg.
2. Once you have decided on the pattern, select the kit according to the desired speed and stroke.
3. Place your order by the kit number.

pattern E Vertical Load Capacity Less than 5 kg

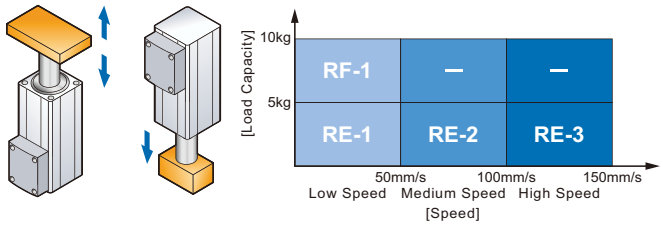
Speed	Kit Configuration			Stroke	Kit Number
Low Speed (50mm/sec)	Actuator		RCP2-RA4C-I-42P -2.5- ① -P3-M-B →P28	50mm	RE-1-050
				100mm	RE-1-100
				150mm	RE-1-150
				200mm	RE-1-200
				250mm	RE-1-250
				300mm	RE-1-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
Medium Speed (100mm/sec)	Actuator		RCP2-RA4C-I-42P -5- ① -P3-M-B →P28	50mm	RE-2-050
				100mm	RE-2-100
				150mm	RE-2-150
				200mm	RE-2-200
				250mm	RE-2-250
				300mm	RE-2-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		
High Speed (150mm/sec)	Actuator		RCP2-RA4C-I-42P -5- ① -P3-M-B →P28	50mm	RE-3-050
				100mm	RE-3-100
				150mm	RE-3-150
				200mm	RE-3-200
				250mm	RE-3-250
				300mm	RE-3-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		

①A placeholder for the value of the desired stroke.
Example: "50" for 50mm

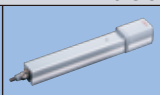
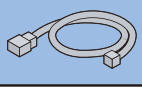
MEC Rod Kit (Vertical Type)

Ordering Example:

If load capacity = less than 5kg, speed = medium speed (200mm/sec), and stroke = 50mm, the bundle package number to order is **RE-2-050**.



pattern F Vertical Load Capacity Less than 10 kg

Speed	Kit Configuration			Stroke	Kit Number
Low Speed (100mm/sec)	Actuator		RCP2-RA4C-I-42P -2.5- ① -P3-M-B →P28	50mm	RF-1-050
				100mm	RF-1-100
				150mm	RF-1-150
				200mm	RF-1-200
				250mm	RF-1-250
				300mm	RF-1-300
	Controller Type		PMEC-C-42PI-NP-2-1		
	Cable		5m cable included		

PMEC 3-position 100/200VAC Controller for RCP2/RCP3

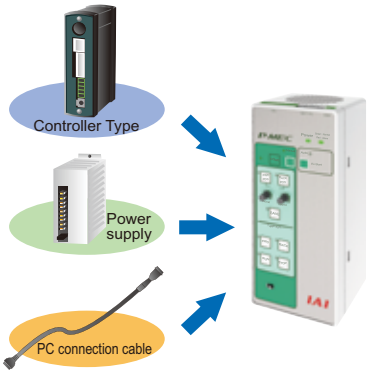
AMEC 3-position 100VAC Controller for RCA/RCA2/RCL

MEC (Mechanical Engineer Control) 3-position Controller for ROBO Cylinders

Features

1 Low Price

The PMEC comes complete with a controller, power supply, acceleration and speed change functions, and all necessary features including a PC connection cable, all at an affordable price. In addition, a MEC-dedicated PC software is available as an option.

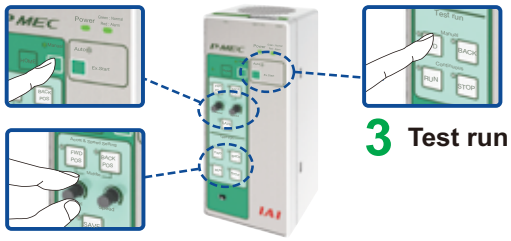


2 Easy to Use

Even first-time users can set up the MEC without a manual. The acceleration and speed settings can be changed with the knobs on the controller.

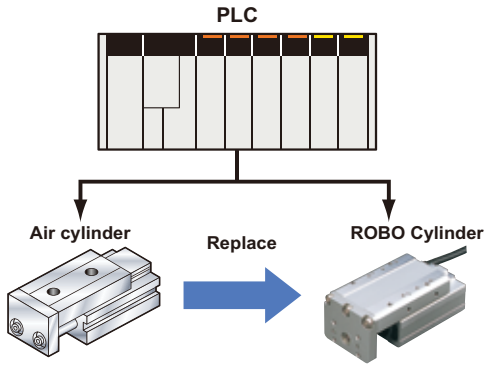
1 Manual

2 Adjust



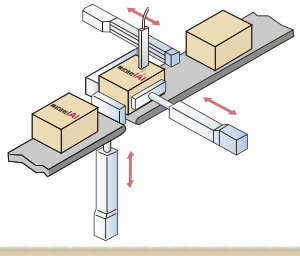
3 Easy to Replace Air Cylinders

The very same signals that drive the air cylinders can drive ROBO Cylinders. Hence you can continue using your current PLC programs without any modification.



4 Supports Press/Intermediate Stop Operations

ROBO Cylinders support press operations similar to air cylinders.
In addition, the MEC-dedicated PC software allows you to configure intermediate stop at any position between the home position and stroke end position.



List of Models

Series	PMEC		AMEC
Appearance			
Supported Actuators	RCP2/RCP3		RCA/RCA2/RCL
Power Supply Voltage	100V	100-240V	100V
Accessories	AC power supply cable (2m) USB cable (3m) I/O cable (2m) I/O connector EMG connector Standard mounting bracket		

Model

PMEC — C — ☐ I — ☐ — 2 — ☐

Series | Type | Motor Type | Encoder Type | I/O Type | I/O Cable Length | Power Supply Voltage

Type	
C	Standard Type

Encoder Type	
I	Incremental Type

I/O Type	
NP	NPN Type
PN	PNP Type

I/O Cable Length	
2	2m

Power Supply Voltage	
1	Single-phase 100VAC
2	Single-phase 100 to 240VAC

Motor Type	
20P	For 20-☐ pulse motors
28P	For 28-☐ pulse motors
28SP	For 28-☐ pulse motors (dedicated to RA3C)
35P	For 35-☐ pulse motors
42P	For 42-☐ pulse motors
56P	For 56-☐ pulse motors

AMEC — C — ☐ I — ☐ — 2 — 1

Series | Type | Motor Type | Encoder Type | I/O Type | I/O Cable Length | Power Supply Voltage

Type	
C	Standard Type

Encoder Type	
I	Incremental Type

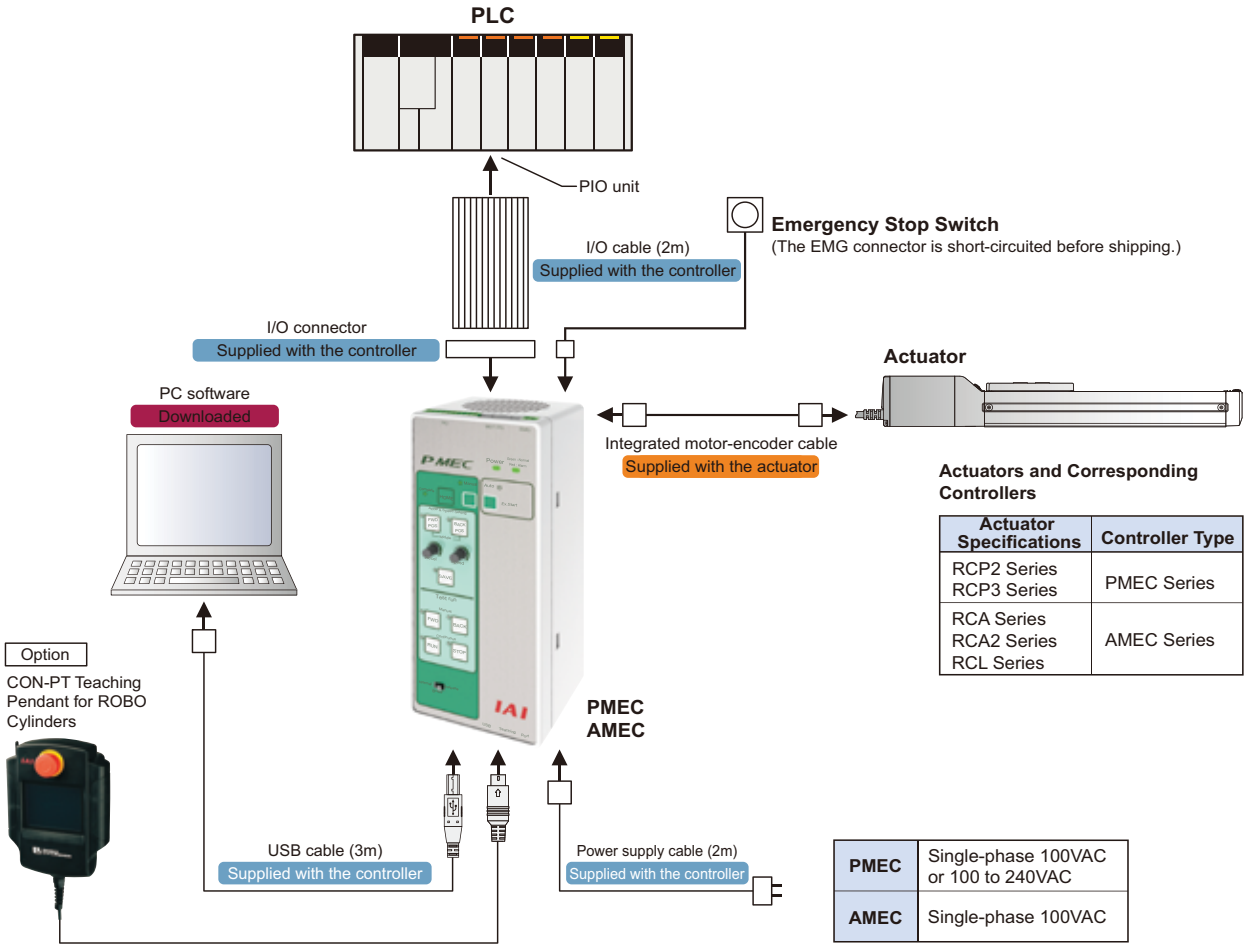
I/O Type	
NP	NPN Type
PN	PNP Type

I/O Cable Length	
2	2m

Power Supply Voltage	
1	Single-phase 100VAC

Motor Type	
2	For 2W motors
5	For 5W motors
10	For 10W motors
20	For 20W motors
20S	For 20W motors (dedicated to RCA2-SA4C/RCA-RA3x)
30	For 30W motors

System Configuration



Actuators and Corresponding Controllers

Actuator Specifications	Controller Type
RCP2 Series RCP3 Series	PMEC Series
RCA Series RCA2 Series RCL Series	AMEC Series

PMEC	Single-phase 100VAC or 100 to 240VAC
AMEC	Single-phase 100VAC

I /O Signal Table

Operating pattern			2-Position Stop	3-Position Stop
Pin No.	Wire Color	Signal Type	Signal Name	Signal Name
1	Brown	PIO power supply	24V	24V
2	Red		0V	0V
3	Orange	Input	ST0 (Solenoid A: ON moves to the end position, and OFF moves to the home position.)	ST0 (Solenoid A: MOVE signal 1)
4	Yellow		–	ST1 (Solenoid B: MOVE signal 2)
5	Green		RES (Alarm reset)	RES (Alarm reset)
6	Blue		–	–
7	Purple	Output	LS0 (Home position detected)/PE0 (Home positioning complete) *1	LS0 (Home position detected)/PE0 (Home positioning complete)*1
8	Gray		LS1 (End position detected)/PE1 (End positioning complete) *1	LS1 (End position detected)/PE1 (End positioning complete) *1
9	White		HEND (home return complete)	LS2 (Intermediate point detected)/PE2 (Intermediate positioning complete)*1
10	Black		* ALM (alarm) *2	* ALM (alarm)*2

* 1: Signals PE0 through PE2 will be output if the press function was enabled in the initial setting. Otherwise, LS0 through LS2 will be output.
* 2: The ALM signal is normally ON, and turns OFF when an alarm occurs.

MEC PC Software

Please contact IAI technical support for more information.

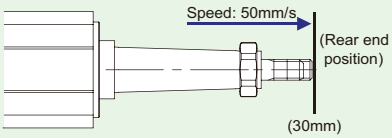
www.intelligentactuator.com

Operation Patterns

PIO Pattern (2-point travel)

This movement pattern consists of a movement between two positions (front and rear positions). You can easily set the front and rear positions by entering the numbers into the controller using the MEC PC software or the optional Teaching Pendant. There are two movements in this pattern. In the "Positioning" movement, the rod and the slider move to the specified position, and in the "Press" movement, the rod is pressed onto the work piece.

Pointing



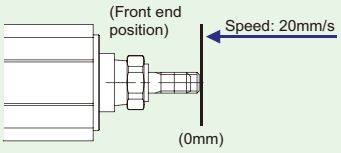
Input Signal

ST0	Solenoid A	ON

When ST0 is turned ON, the rod moves to the rear end position (at a coordinate of 30mm) at a speed of 50mm/s.

Rear end position data

Position	30mm
Speed	50mm/s
Pressing Force	—
Width	—



Input Signal

ST0	Solenoid A	OFF

When ST0 is turned OFF, the rod returns to the front end position (at a position of 0mm) at a speed of 20mm/s.

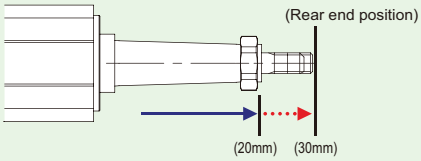
Front end position data

Position	0mm
Speed	20mm/s
Pressing Force	—
Width	—

PIO Pattern (2-point travel)

This pattern of operation consists of a movement between two positions (Front end and rear end positions) for a "press operation", in which the rod is pressed onto the workpiece.

Press Operation



Input Signal

ST0	Solenoid A	ON

When Input 0 is turned on, the rod moves up to the 20mm position at a speed of 80mm/s. Then the pressing will take place from the 20mm position to the 30mm position at low speed.

Rear end position data

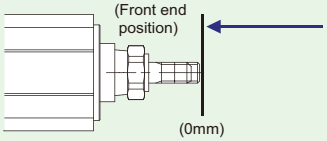
Position	30mm
Speed	80mm/s
Pressing Force	50%
Width	10mm

* The press operation is enabled when there is a numerical value specified for the pressing force in the position data of the controller. (If no numeric value is specified for the pressing force, it will default to positioning operation.)

PIO Pattern (3-point travel)

This pattern of operation consists of a movement between three positions (front end, intermediate, and rear end positions). Movement positions are switched with a combination of two signals, i.e., ST0 and ST1.

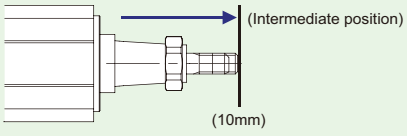
Positioning



Input Signal

ST0	Solenoid A	ON
ST1	Solenoid B	OFF

If only ST0 is turned ON, the rod moves to the front end position at the acceleration or speed that you specified.

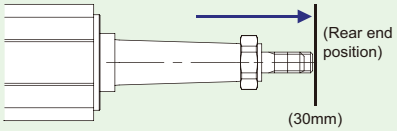


Input Signal

ST0	Solenoid A	ON*
ST1	Solenoid B	ON*

If both ST0 and ST1 are turned ON, the rod moves to the intermediate position at the acceleration or speed that you specified.
Turning both signals OFF will cause the rod to stop in place.

* You can also configure the initial settings so that the rod will move to the intermediate position with both signals turned OFF, and stop in place with both signals turned ON.



Input Signal

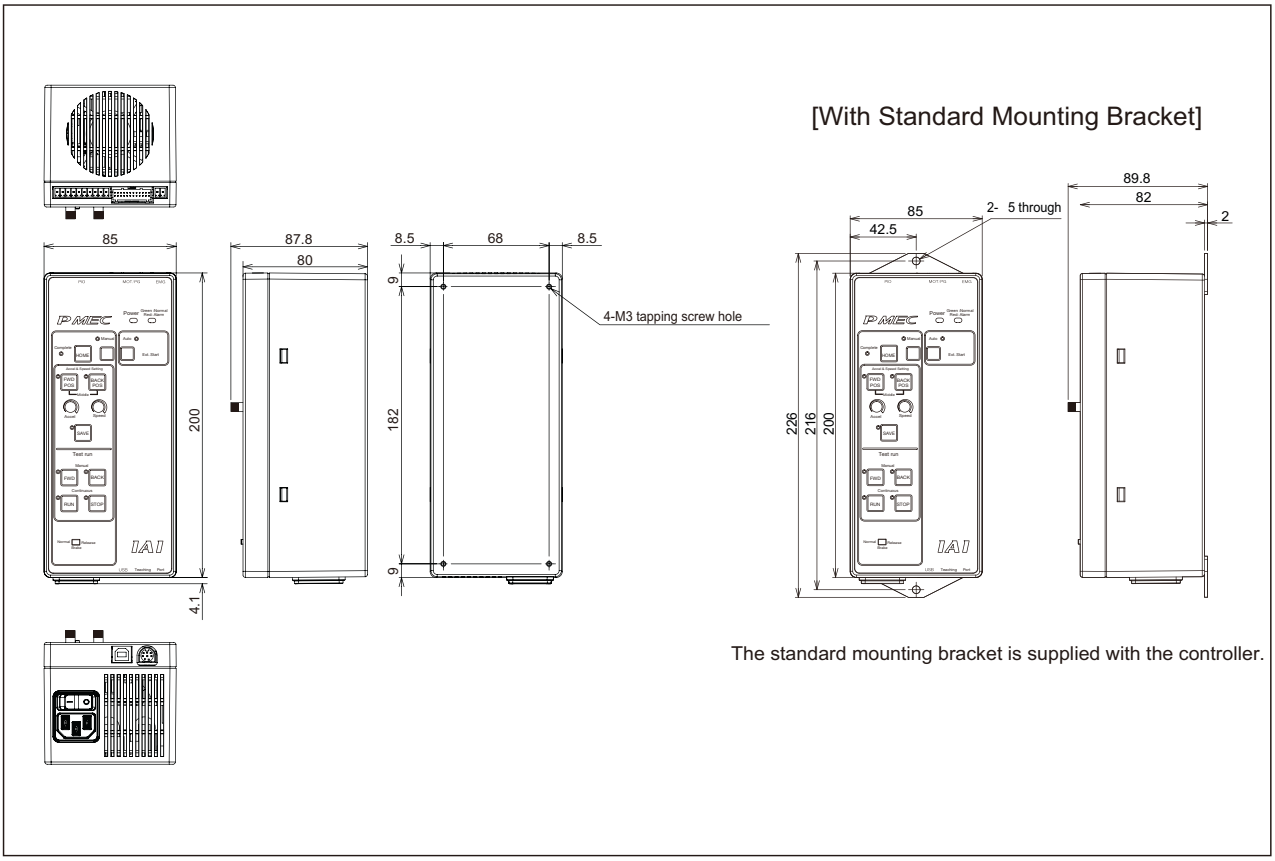
ST0	Solenoid A	OFF
ST1	Solenoid B	ON

If only ST1 is turned ON, the rod moves to the rear end position at the acceleration or speed that you specified.

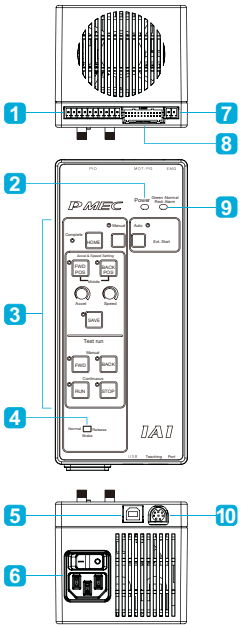
Specifications

Item	Specification		
Controller Type	PMEC		AMEC
Actuator Specifications	RCP2/RCP3 Series Actuator		RCA/RCA2/RCL Series Actuator
Number of control axes	Single axis		
Operating mode	Positioner type		
Number of positions	2/3		
Backup memory	EEPROM		
I/O connector	10-pin terminal block		
I/O points	4 input points/4 output points		
I/O power supply	External power supply at 24 VDC ± 10%		
Serial communication	RS485: 1 ch/USB: 1 ch		
Position detection method	Incremental encoder		
Power Supply Voltage	AC100V±10%	AC100V-240V±10%	AC100V±10%
Rated current	1.3A	0.67A(AC100V)/0.36A(AC200V)	2.4A
Inrush current	30A	15A(AC100V)/30A(AC200V)	15A
Leak current	0.5mA or less	0.40mA max(AC100V) 0.75mA max(AC200V)	0.50mA or less
Dielectric strength	DC500V 1MΩ		
Vibration resistance	Single amplitudes of 0.035mm (continuous) and 0.075mm (intermittent) at 10 to 57Hz 4.9 m/s² (continuous) and 9.8 m/s² (intermittent) at 57 to 150 Hz.Vibration resistance in X, Y, and Z directions		
Ambient operating temperature	0~40ºC		
Ambient operating humidity	10% to 85% RH (no condensation)		
Ambient operating atmosphere	No corrosive gas		
Enclosure rating	IP20		
Weight	395g	410g	505g

Dimensions



Part Names and Functions



1 PIO connector ····· Used for I/O connection with an external controller, such as a PLC.

2 Power LED ····· Lit green when the power is turned on.

3 Control Panel ····· See below.

4 Brake switch

Release	Used to release the brake of the actuator.
Normal	Used to control the brake of the actuator.

5 USB connector ····· Used for USB connection with the computer when using the MEC PC software.

6 AC inlet ····· Used for inserting the power supply cable.

7 EMG connector ····· Used to connect to the emergency stop button. Short-circuit the connector if no emergency stop button is used.

8 MOT/PG connector ·· Used for inserting the cable to connect with the actuator.

9 Status LED

RUN (green)	Indicates the status of the servo. On: Servo ON; Off: Servo OFF (energy-saving mode) Flashing (1Hz): Auto servo OFF
ALM (red) EMG (red)	The LED flashes if an alarm is turned ON or if the controller has come to an emergency stop.

10 SIO connector ····· Used to connect to the CON-PT or SEP-PT Teaching Pendant.

Control Panel

HOME button
At the start of operation, first hme and verify the position at 0mm.

MANUAL button
Press this button to set the acceleration and/or speed, or to start a test run.
(Press for at least one second.)

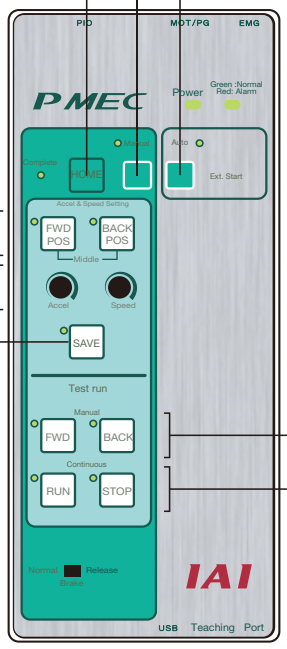
AUTO button
Press this button for at least one second to operate the controller with commands from the MEC PC software or a PLC. (Press for at least one second.)

Acceleration and Maximum Speed Settings
Configure the movement of the actuator.

FWD POS / BACK POS button
Use these buttons to switch to the movement you want to configure:
FWD POS: Movement toward the end position.
BACK POS: Movement toward the home position
MIDDLE: Movement toward the intermediate position.
(Enabled in the MEC PC software and switched on by pressing "FWD POS" and "BACK POS" buttons simultaneously. Pressing these buttons is disabled for 2-position travel.)

Acceleration / Speed knobs
Use these knobs to set the speed/acceleration between 1 to 100% of the maximum speed and rated acceleration/deceleration.
* The minimum speed may be less than 1% in some cases.

SAVE button
Use this button to save the speed and acceleration settings.



Test run
Physically moves the actuator so you can verify the registered movement.

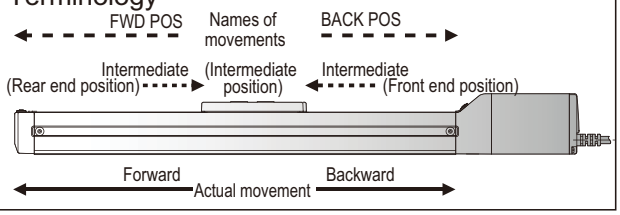
FWD button
Moves the actuator toward the rear end position. In a 2-position travel, the actuator moves from the front end position to the rear end position. In a 3-position travel, the actuator moves from the front end position to the intermediate position, then to the rear end position.

BACK button
Moves the actuator back to the front end position.

RUN button
Starts continuous operation of the actuator. In a 2-position travel, the actuator moves back and forth between the front end and rear end positions. In a 3-position travel, the actuator repeats its movement from the front end position intermediate position rear end position front end position.

STOP button
Stops the above operation.

Terminology



Options

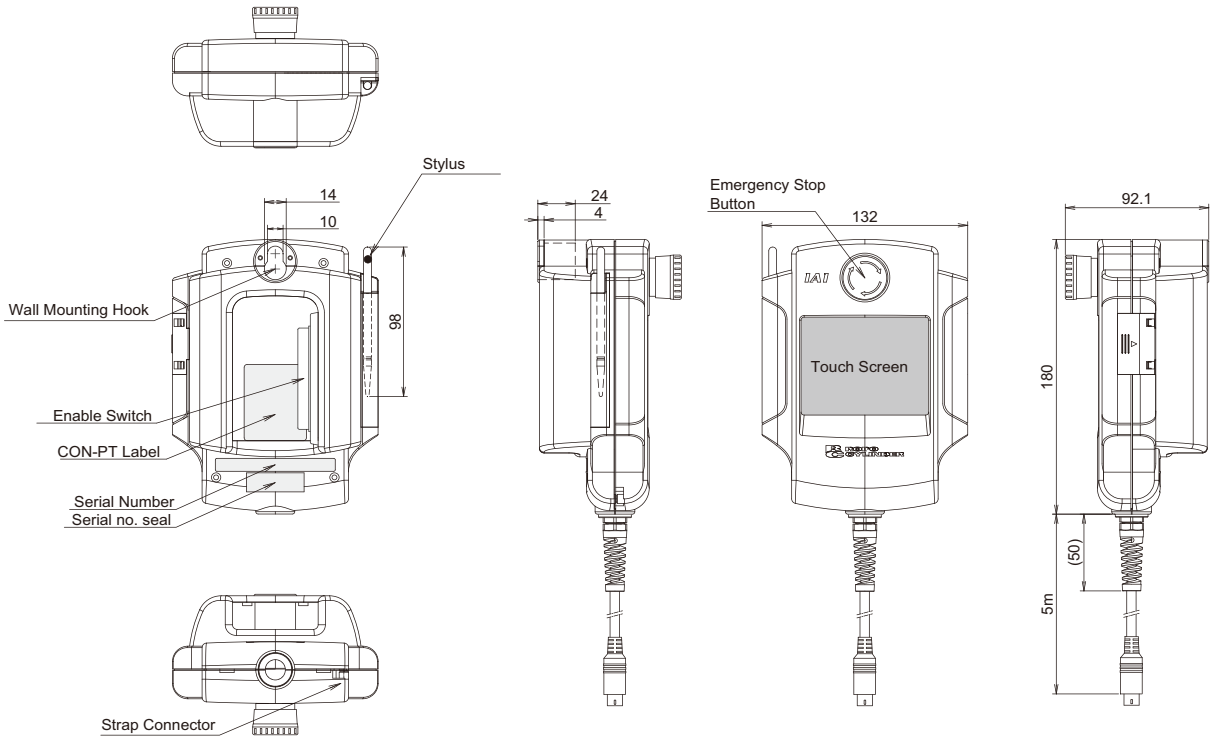
●Teaching Pendant for Position Controller

Features The Teaching Pendant is a data input device equipped with an interactive touch panel that is easy to use even for first-time users.
You can configure various settings, such as the front end, rear end, and intermediate positions, speed, pressing force, as well as make operational adjustments such as jogging, inching, and movement to reference positions.

■Model/Specifications/Pricing

Item		Description
Model	Japanese version	CON-PT-M
	English version	CON-PT-M-ENG
Type		Standard type
Features		Position data entry/editing Move function (Move to position, Jog function, Inching function) I/O signal test Parameter editing Language change (Japanese/English)
Display		3-color LED backlight
Ambient Operating Temp/Humidity		0~50°C 20~85%RH(no condensation)
Environmental resistance		IP40
Weight (including 5m cable)		Approximately 750g
Accessory		Stylus

■Part Names/Dimensions

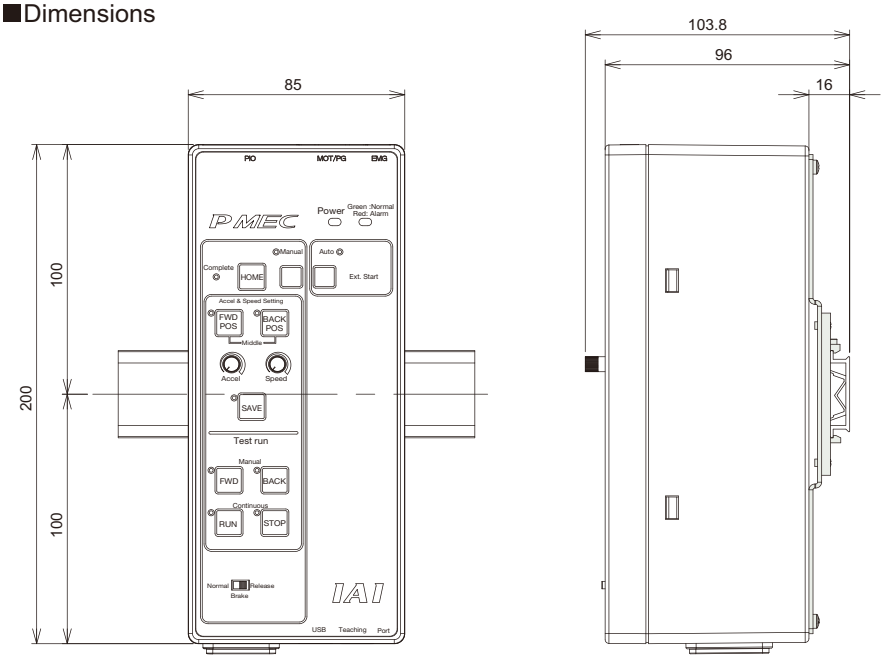


■Options

·**STR-1** Strap

●DIN Rail Mounting Bracket MEC-AT-D

■Dimensions



●Maintenance Cable

■List of Maintenance Cable Models and Pricing

Type		Cable Length	Model
Integrated motor-encoder cable	PMEC ⟷ RCP3 AMEC ⟷ RCA2/RCL	1m	CB-APSEP-MPA010
		3m	CB-APSEP-MPA030
		5m	CB-APSEP-MPA050
	PMEC ⟷ RCP2	1m	CB-PSEP-MPA010
		3m	CB-PSEP-MPA030
		5m	CB-PSEP-MPA050
	AMEC ⟷ RCA	1m	CB-ASEP-MPA010
		3m	CB-ASEP-MPA030
		5m	CB-ASEP-MPA050
I/O cable		2m	CB-APMEC-PIO020-NC
		3m	CB-APMEC-PIO030-NC
		5m	CB-APMEC-PIO050-NC
USB cable		3m	CB-SEL-USB030

Slider (Vertical)

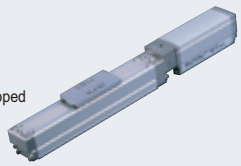
ROBO Cylinder (Slider Type) RCP3-SA3C

Body Width: 32mm
Pulse Motor, Coupling Type

Model Descriptions

RCP3 — SA3C — I — 28P — 4 — ☐ — P3 — M — B

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller	Cable Length	Option
RCP3	SA3C	I : Incremental	28P : Pulse motor (28 x 28 in size)	4 : 4mm	50 : 50mm to 300 : 300mm (Set stroke every 50mm)	P3 : PMEC	M : 5m	B : Brake-equipped



* See page 30 for model descriptions.

Actuator Specifications

Lead and Load Capacity

Model	Lead (mm)	Maximum Load Capacity Horizontal (kg)	Maximum Load Capacity Vertical (kg)	Maximum Pressing Force (N)	Stroke (mm)
RCP3-SA3C-I-28P-4-① -P3-M-B	4	2	1	22	50~300 (every 50mm)

Legend ① Stroke

Stroke and Maximum Speed

Lead \ Stroke	50~300(every 50mm)
4	200

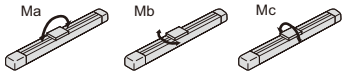
(Unit: mm/s)

Actuator Specifications

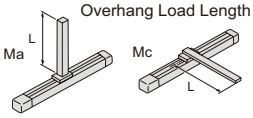
Item	Description
Drive Method	Ball screw Φ6mm, rolled C10
Positioning Repeatability	±0.02 mm
Lost Motion	0.1 mm max.
Base	Material: Aluminum with special alumite processing
Allowable Static Moment	Ma:5.0N•m Mb:7.1N•m Mc:7.9 N•m
Allowable Dynamic Moment *	Ma:1.96N•m Mb:2.84N•m Mc:3.14N•m
Overhang Load Length	100 mm max.
Ambient Operating Temp/Humidity	0°C to 40°C at 85% RH or less (no condensation)

* For a 5,000km running life.

Direction of Allowable Load Moment



Overhang Load Length



POINT Note

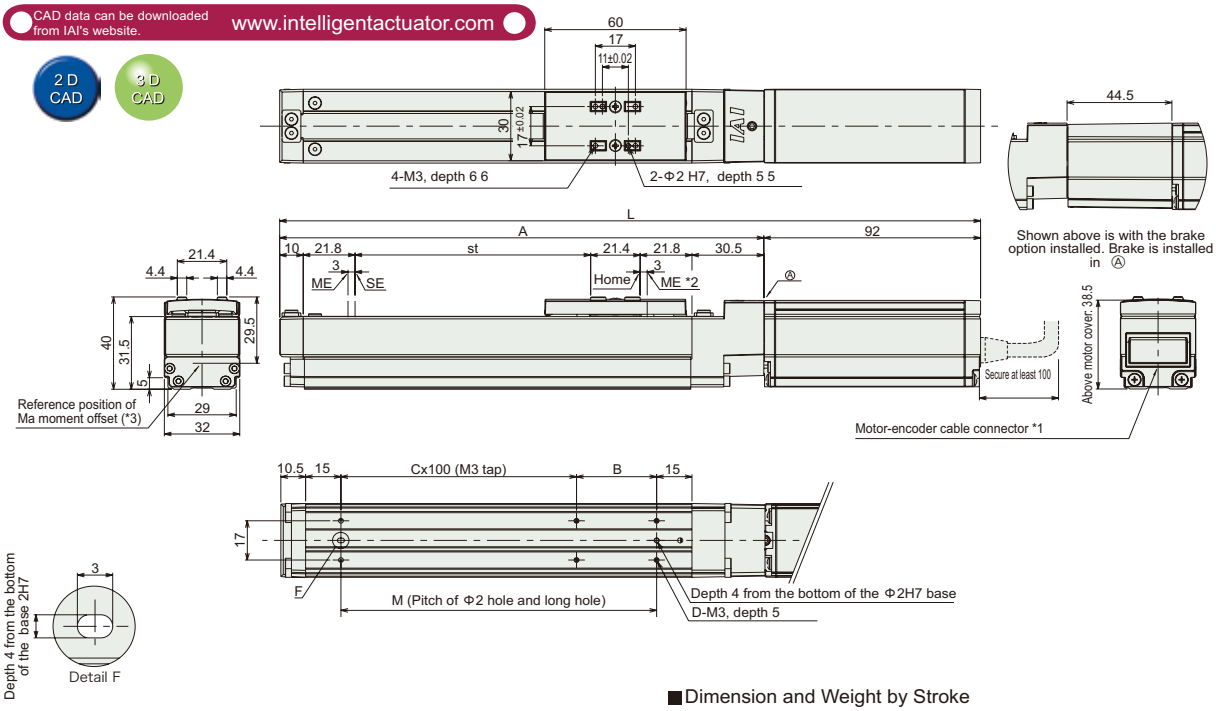
(1) Because the RCP3 series uses a pulse motor, the load capacity decreases at high speeds. Refer to the *Correlation Diagram of Speed and Load Capacity* on page 29 and check the load capacity at the desired speed.

(2) The load capacity is based on operation at an acceleration of 0.3G (or 0.2G for vertical operation).

Dimensional Drawing

CAD data can be downloaded from IAI's website. www.intelligentactuator.com

2D CAD 3D CAD



Dimension and Weight by Stroke

Stroke		50	100	150	200	250	300
L	No brake	247.5	297.5	347.5	397.5	447.5	497.5
	Brake-equipped	292	342	392	442	492	542
A		155.5	205.5	255.5	305.5	355.5	405.5
B		84	34	84	34	84	34
C		0	1	1	2	2	3
D		4	6	6	8	8	10
M		84	134	184	234	284	334
Weight (kg)		0.7	0.7	0.8	0.9	0.9	1

* The brake increases the weight by 0.2kg.

*1. Connect the motor-encoder cable (integrated).
*2. The slider will move to position ME after the actuator returns to the origin. Make sure that the slider will not interfere with any peripheral objects.
ME: Mechanical end
SE: Stroke end
*3. This is a reference position for calculating the Ma moment.

Slider (Vertical/Horizontal)

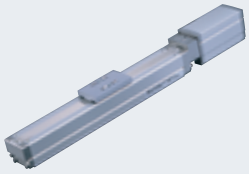
ROBO Cylinder (Slider Type) RCP3-SA4C

Body Width: 40mm
Pulse Motor, Coupling Type

Model Descriptions

RCP3 – SA4C – I – 35P – ☐ – ☐ – P3 – M – ☐

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller	Cable Length	Option
		I : Incremental	35P Pulse motor 35 x 35 size	10 :10mm 5 : 5mm	50 : 50mm to 500 : 500mm (Set stroke every 50mm)	P3 :PMEC	M : 5m	B : Brake



* See page 30 for model descriptions.

Actuator Specifications

Lead and Load Capacity

Model	Lead (mm)	Maximum Load Capacity Horizontal	Maximum Load Capacity Vertical	Maximum Pressing Force (N)	Stroke (mm)
RCP3-SA4C-I-35P-10-①-P3-M	10	2	~1.5	34	50~500 (every 50mm)
RCP3-SA4C-I-35P-5-①-P3-M-B	5	~9	~4	68	

Stroke and Maximum Speed

Lead \ Stroke	50~500(every 50mm)
10	500
5	250

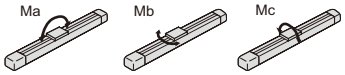
(Unit: mm/s)

Actuator Specifications

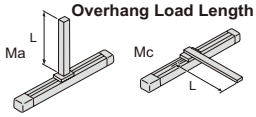
Item	Description
Drive Method	Ball screw, Φ8mm, rolled C10
Positioning Repeatability	± 0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum with special alumite treatment
Allowable Static Moment	Ma:6.8N•m Mb:9.7N•m Mc:13.3N•m
Allowable Dynamic Moment *	Ma:3.04N•m Mb:4.31N•m Mc:5.00N•m
Overhang Load Length	120 mm or less
Ambient Operating Temp/Humidity	0°C to 40°C at 85% RH or less (no condensation)

* For a 5,000km running life.

Direction of Allowable Load Moment



Overhang Load Length



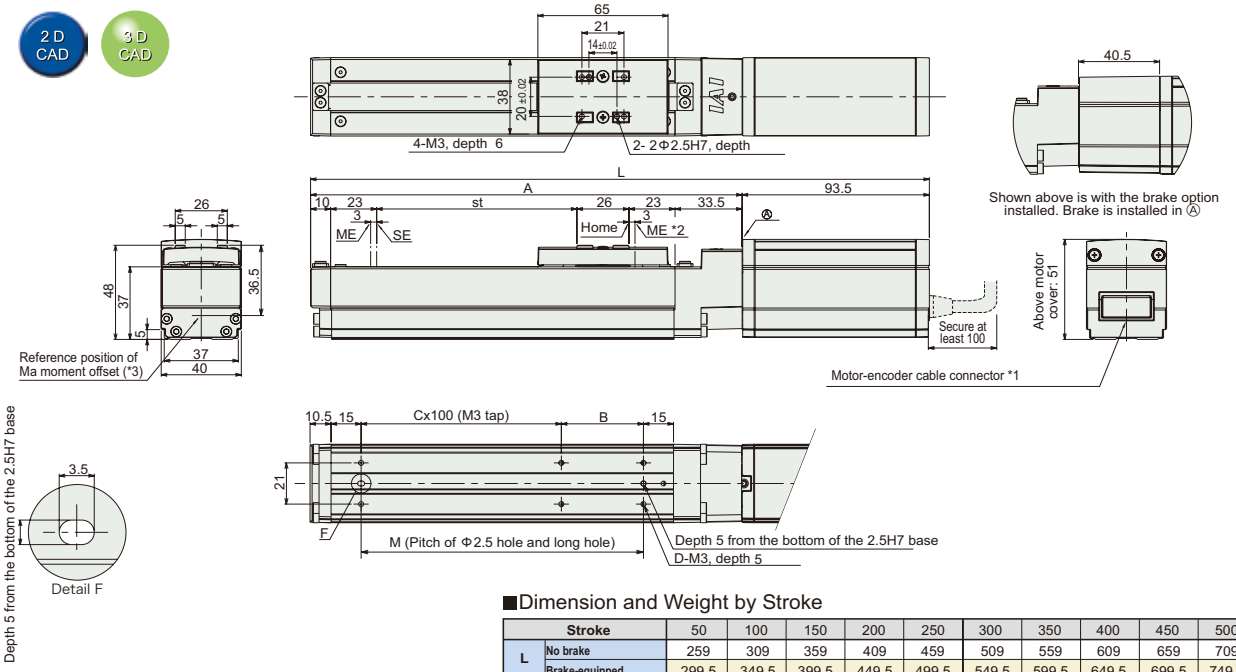
POINT Note

(1) Because the RCP3 series uses a pulse motor, the load capacity decreases at high speeds. Refer to the *Correlation Diagram of Speed and Load Capacity* on page 29 and check the load capacity at the desired speed.
(2) The load capacity is based on operation at an acceleration of 0.3G (or 0.2G for vertical operation).

Dimensional Drawing

CAD data can be downloaded from IAI's website. www.intelligentactuator.com

2D CAD 3D CAD

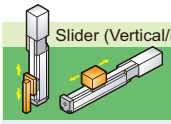


Dimension and Weight by Stroke

Stroke		50	100	150	200	250	300	350	400	450	500
L	No brake	259	309	359	409	459	509	559	609	659	709
	Brake-equipped	299.5	349.5	399.5	449.5	499.5	549.5	599.5	649.5	699.5	749.5
A		165.5	215.5	265.5	315.5	365.5	415.5	465.5	515.5	565.5	615.5
B		91	41	91	41	91	41	91	41	91	41
C		0	1	1	2	2	3	3	4	4	5
D		4	6	6	8	8	10	10	12	12	14
M		91	141	191	241	291	341	391	441	491	541
Weight (kg)		0.9	1	1.1	1.2	1.3	1.4	1.5	1.6	1.5	1.5

* The brake increases the weight by 0.3 kg.

*1. Connect the motor-encoder cable (integrated).
*2. The slider will move to position ME after the actuator returns to the origin. Make sure that the slider will not interfere with any peripheral objects.
ME: Mechanical end
SE: Stroke end
*3. This is a reference position for calculating the Ma moment.



Slider (Vertical/Horizontal)

ROBO Cylinder (Slider Type) RCP3-SA5C

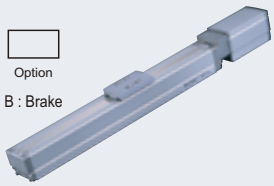
Body Width: 52mm
Pulse Motor, Straight Type

■ Model Number

RCP3 – SA5C – I – 42P – ☐ – ☐ – P3 – M – ☐

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller	Cable Length	Option
RCP3	SA5C	I : Incremental	42P : Pulse Motor (42 x 42 in size)	12 : 12mm 6 : 6mm 3 : 3mm	50 : 50mm to 800 : 800mm (Set stroke every 50mm)	P3 :PMEC	M : 5m	B : Brake

* See page 30 for model descriptions.



Actuator Specifications

■ Lead and Load Capacity

Model	Lead (mm)	Maximum Load Capacity Horizontal (kg)	Maximum Load Capacity Vertical (kg)	Max. pressing force (N)	Stroke (mm)
RCP3-SA5C-I-42P-12-①-P3-M	12	~6	~2	47	50~800 (every 50mm)
RCP3-SA5C-I-42P-6-①-P3-M-B	6	~10	~5	95	
RCP3-SA5C-I-42P-3-①-P3-M-B	3	~19	~10	189	

Legend: ① Stroke

■ Stroke and Maximum Speed

Lead \ Stroke	50 to 550 (every 50mm)	600 (mm)	650 (mm)	700 (mm)	750 (mm)	800 (mm)
12	600	570	490	425	370	330
6	300	285	245	210	185	165
3	150	140	120	105	90	80

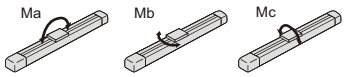
(Unit: mm/s)

Actuator Specifications

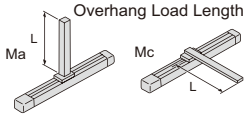
Item	Description
Driving method	Ball screw, ϕ10mm, rolled C10
Positioning Repeatability	± 0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum with special alumite treatment
Allowable Static Moment	Ma:10.2N•m Mb:14.6N•m Mc:22.4N•m
Allowable Dynamic Moment *	Ma:3.92N•m Mb:5.58N•m Mc:8.53N•m
Overhang Load Length	130mm or less
Ambient Operating Temp/Humidity	0°C to 40°C at 85% RH or less (no condensation)

* For a 5,000km running life.

Direction of Allowable Load Moment



Overhang Load Length



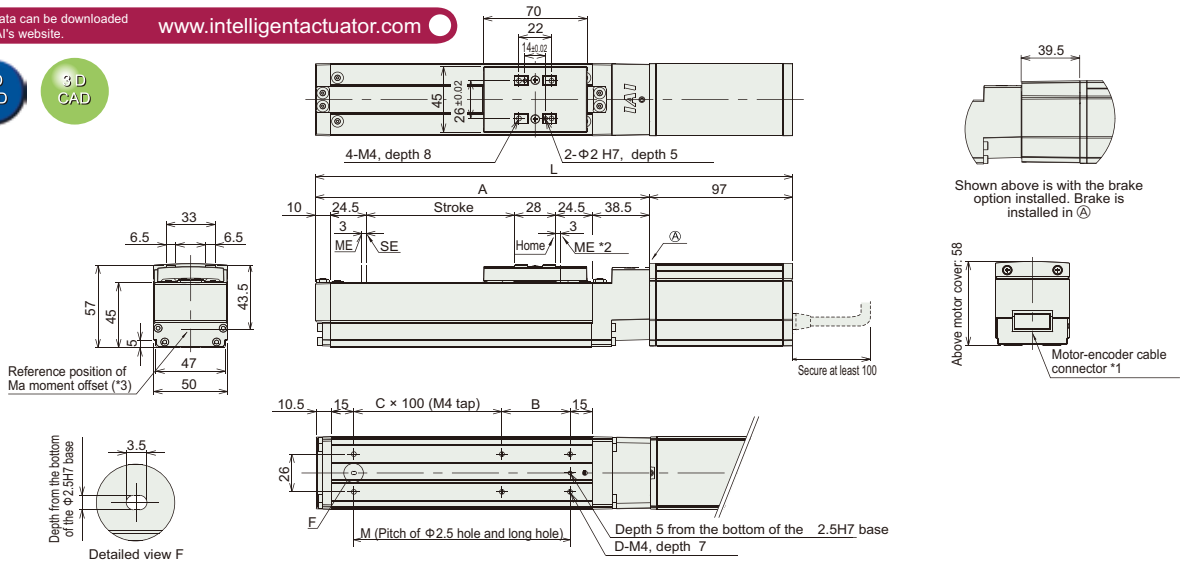
POINT Note

(1) Because the RCP3 series uses a pulse motor, the load capacity decreases at high speeds. Refer to the *Correlation Diagram of Speed and Load Capacity* on page 29 and check the load capacity at the desired speed.
(2) The load capacity is based on operation at an acceleration of 0.3G (or 0.2G for vertical operation).

Dimensional Drawing

CAD data can be downloaded from IAI's website. www.intelligentactuator.com

2D CAD 3D CAD

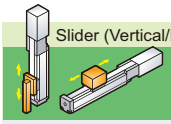


*1 Connect the motor-encoder cable (integrated).
*2 The slider will move to position ME after the actuator returns to the origin. Make sure that the slider will not interfere with any peripheral objects.
*3 This is a reference position for calculating the Ma moment.

■ Dimension and Weight by Stroke

Stroke		50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	No brake	272.5	322.5	372.5	422.5	472.5	522.5	572.5	622.5	672.5	722.5	772.5	822.5	872.5	922.5	972.5	1022.5
	Brake-equipped	312	362	412	462	512	562	612	662	712	762	812	862	912	962	1012	1062
A		175.5	225.5	275.5	325.5	375.5	425.5	475.5	525.5	575.5	625.5	675.5	725.5	775.5	825.5	875.5	925.5
B		96	46	96	46	96	46	96	46	96	46	96	46	96	46	96	46
C		0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8
D		4	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20
M		96	146	196	246	296	346	396	446	496	546	596	646	696	746	796	846
Weight (kg)		1.4	1.5	1.6	1.8	1.9	2	2.2	2.3	2.5	2.6	2.7	2.9	3.0	3.2	3.3	3.4

* The brake increases the weight by 0.4kg.



Slider (Vertical/Horizontal)

ROBO Cylinder (Slider Type) RCP2-SA5C

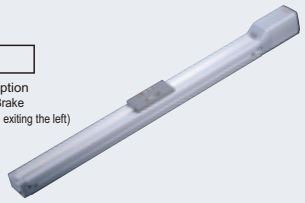
Body Width: 52mm
Pulse Motor, Straight Type

■ Model Number

RCP2-SA5C – I – 42P – □ – □ – P3 – M – □

- Series: RCP2-SA5C
- Type: I
- Encoder Type: I : Incremental
- Motor Type: 42P:Pulse Motor (42 x 42 in size)
- Lead: 12 : 12mm, 6 :6mm
- Stroke: 50 : 50mm to 800 : 800mm (Set stroke every 50mm)
- Applicable Controller: P3:PMEC
- Cable Length: M : 5m
- Option: BL : Brake (Cable exiting the left)

* See page 30 for model descriptions.



Actuator Specifications

■ Lead and Load Capacity

Model	Lead (mm)	Maximum Load Capacity Horizontal (kg)	Maximum Load Capacity Vertical (kg)	Stroke (mm)
RCP2-SA5C-I-42P-12-①-P3-M	12	~6	1	50 to 800 (every 50mm)
RCP2-SA5C-I-42P-6-①-P3-M-BL	6	~13	~4	

Legend: ① Stroke

■ Stroke and Maximum Speed

Lead \ Stroke	50 to 550 (every 50mm)	600 (mm)	650 (mm)	700 (mm)	750 (mm)	800 (mm)
12	600	540	460	400	360	300
6	300	270	230	200	180	150

(Unit: mm/s)

Actuator Specifications

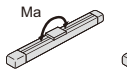
Item	Description
Driving method	Ball screw, Φ10mm, rolled C10
Positioning Repeatability	± 0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum with special alumite treatment
Allowable Static Moment	Ma: 18.6N•m Mb: 26.6N•m Mc: 47.5N•m
Allowable Dynamic Moment *	Ma: 4.9N•m Mb: 6.8N•m Mc: 11.7N•m
Overhang Load Length	Ma direction: Mb/Mc directions: 150 mm or less
Ambient Operating Temp/Humidity	0°C to 40°C at 85% RH or less (no condensation)

* The permissible dynamic moment values are provided on the condition that the actuator has a travelling life of 5,000 km.`

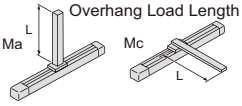
POINT Note

(1) As the stroke length increases, the maximum speed decreases due to hazardous ball screw RPMs. Check the maximum desired stroke speed in the Actuator Spec Table below.
(2) Because the RCP2 series uses a pulse motor, the load capacity decreases at high speeds. Refer to the Correlation Diagram of Speed and Load Capacity on page 29 and check the load capacity at the desired speed.
(3) The load capacity is based on operation at an acceleration of 0.3G (or 0.2G for vertical operation with lead 3). The above values are the upper limit for the acceleration.

Direction of Allowable Load Moment



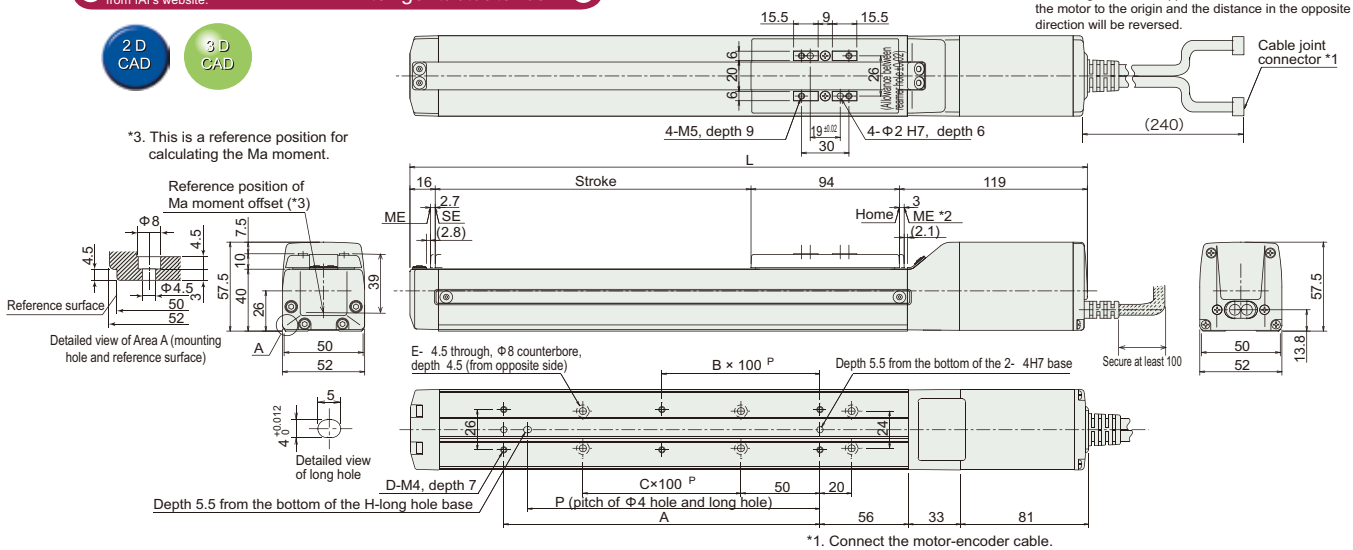
Overhang Load Length



Dimensional Drawing

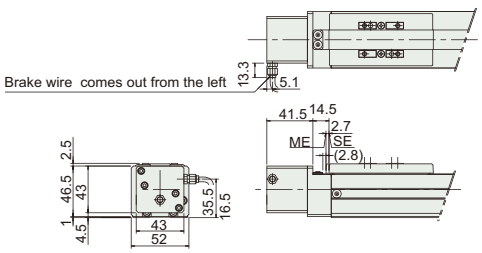
CAD data can be downloaded from IAI's website. www.intelligentactuator.com

2D CAD 3D CAD



*1. Connect the motor-encoder cable.
*2. The slider will move to position ME after the actuator returns to the origin. Make sure that the slider will not interfere with any peripheral objects.
ME: Mechanical end; SE: Stroke end
Dimensions in parentheses are reference values.

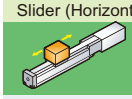
Brake dimensions



■ Dimension and Weight by Stroke

Stroke L	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	279	329	379	429	479	529	579	629	679	729	779	829	879	929	979	1029
A	73	100	100	200	200	300	300	400	400	500	500	600	600	700	700	800
B	0	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7
C	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7
D	4	4	4	6	6	8	8	10	10	12	12	14	14	16	16	18
E	4	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18
H	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
P	0	85	85	185	185	285	285	385	385	485	485	585	585	685	685	785
Weight (kg)	1.5	1.6	1.7	1.8	1.9	2.1	2.2	2.3	2.4	2.5	2.6	2.8	2.9	3.0	3.1	3.2

Slider (Horizontal)



ROBO Cylinder (Slider Type) RCP2-SA7C

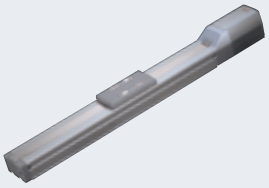
Body Width: 73mm
Pulse Motor, Straight Type

■ Model Number

RCP2 SA7C – I – 56P – 16 – □ – P3 – M

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller	Cable Length
		I : Incremental	56P : Pulse Motor (56 x 56 in size)	16 : 16mm	50 : 50mm to 800 : 800mm (Set stroke every 50mm)	P3 :PMEC	M : 5m

* See page 30 for model descriptions.



Actuator Specifications

■ Lead and Load Capacity

Note 1: Please note that the maximum load capacity will decrease when the speed increases.

Model	Lead (mm)	Maximum Load Capacity Horizontal (kg)	Maximum Load Capacity Vertical (kg)	Stroke (mm)
RCP2-SA7C-I-56P-16-①-P3-M	16	~35	-	50 to 800 (every 50mm)

Legend: ① Stroke

■ Stroke and Maximum Speed

Lead \ Stroke	50 to 700 (every 50mm)	~800 (mm)
16	533	480

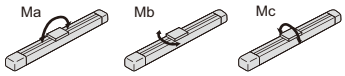
(Unit: mm/s)

Actuator Specifications

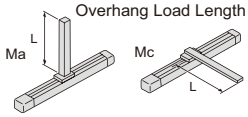
Item	Description
Drive Method	Ball screw, Φ12mm, rolled C10
Positioning Repeatability	± 0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum with special alumite treatment
Allowable Static Moment	Ma: 50.4N·m Mb: 71.9N•m Mc: 138.0N•m
Allowable Dynamic Moment *	Ma: 13.9N•m Mb: 19.9N•m Mc: 38.3N•m
Overhang Load Length	Ma direction: Mb/Mc directions: 230 mm or less
Ambient Operating Temp/Humidity	0°C to 40°C at 85% RH or less (no condensation)

* For a 5,000km running life.

Direction of Allowable Load Moment



Overhang Load Length



POINT Note

(1) As the stroke length increases, the maximum speed decreases due to hazardous ball screw RPMs. Check the maximum desired stroke speed in the Actuator Spec Table below.

(2) Because the RCP2 series uses a pulse motor, the load capacity decreases at high speeds. Refer to the Correlation Diagram of Speed and Load Capacity on page 29 and check the load capacity at the desired speed.

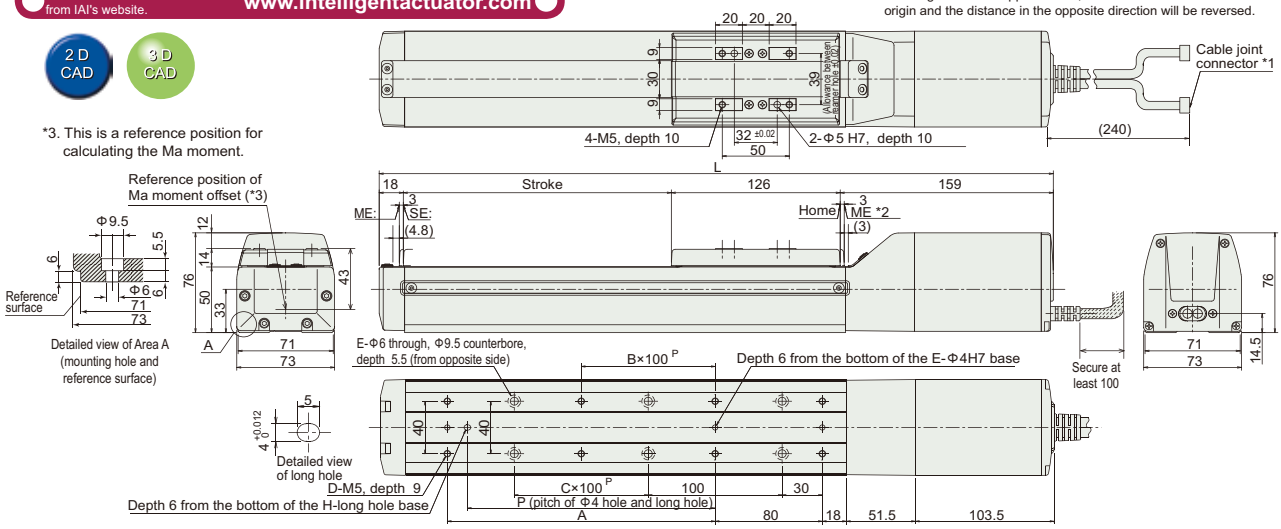
(3) The load capacity is based on operation at an acceleration of 0.3G (or 0.2G for vertical operation with lead 4). The above values are the upper limit for the acceleration.

Dimensional Drawing

CAD data can be downloaded from IAI's website. www.intelligentactuator.com

2D CAD 3D CAD

* If the origin is on the opposite side, the distance from the motor to the origin and the distance in the opposite direction will be reversed.



*1. Connect the motor-encoder cable.
*2. The slider will move to position ME after the actuator returns to the origin. Make sure that the slider will not interfere with any peripheral objects.
ME: Mechanical end; SE: Stroke end
Dimensions in parentheses are reference values.

■ Dimensions and Weight by Stroke

Stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	353	403	453	503	553	603	653	703	753	803	853	903	953	1003	1053	1103
A	0	100	100	200	200	300	300	400	400	500	500	600	600	700	700	800
B	0	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7
C	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7
D	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20
E	2	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
F	4	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18
H	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
P	0	85	85	185	185	285	285	385	385	485	485	585	585	685	685	785
Weight (kg)	3.1	3.3	3.6	3.8	4.0	4.2	4.5	4.7	4.9	5.1	5.4	5.6	5.8	6.0	6.3	6.5

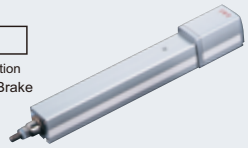
ROBO Cylinder (Rod Type) RCP2-RA4C

Body Width: 73mm
Pulse Motor, Straight Type

■ Model Number

RCP2 – RA4C – I – 42P – □ – □ – P3 – M – □

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller	Cable Length	Option
RCP2	RA4C	I : Incremental	42P : Pulse Motor (42 x 42 in size)	10 : 10mm 5 : 5mm 2.5 : 2.5mm	50 : 50mm to 300 : 300mm (Set stroke every 50mm)	P3 :PMEC	M : 5m	B : Brake



* See page 30 for model descriptions.

Actuator Specifications

■ Lead and Load Capacity

Note 1: Please note that the maximum load capacity will decrease when the speed increases.

Model	Lead (mm)	Maximum Load Capacity Horizontal (kg)	Maximum Load Capacity Vertical (kg)	Max. Pressing Force (N)	Stroke (mm)
RCP2-RA4C-I-42P-10-①-P3-M	10	~25	~4.5	150	50 to 300 (every 50mm)
RCP2-RA4C-I-42P-5-①-P3-M-②	5	~40	~12	284	
RCP2-RA4C-I-42P-2.5-①-P3-M-②	2.5	40	~19	358	

Legend: ① Stroke ② Option: ("B" indicates a model with a brake)

■ Stroke and Maximum Speed

Lead \ Stroke	50 to 200 (every 50mm)	250 (mm)	300 (mm)
10	458	458	350
5	250	237	175
2.5	125 <114>	118 <114>	87

* Values in parenthesis apply to vertical operation.

(Unit: mm/s)

Actuator Specifications

Item	Description
Drive Method	Ball screw, φ8mm, rolled C10
Positioning Repeatability	± 0.02mm
Lost Motion	0.1mm or less
Rod Diameter	φ22mm
Rod Non-rotation Accuracy	±1.5°
Ambient Operating Temp/Humidity	0°C to 40°C at 85% RH or less (no condensation)

POINT Note

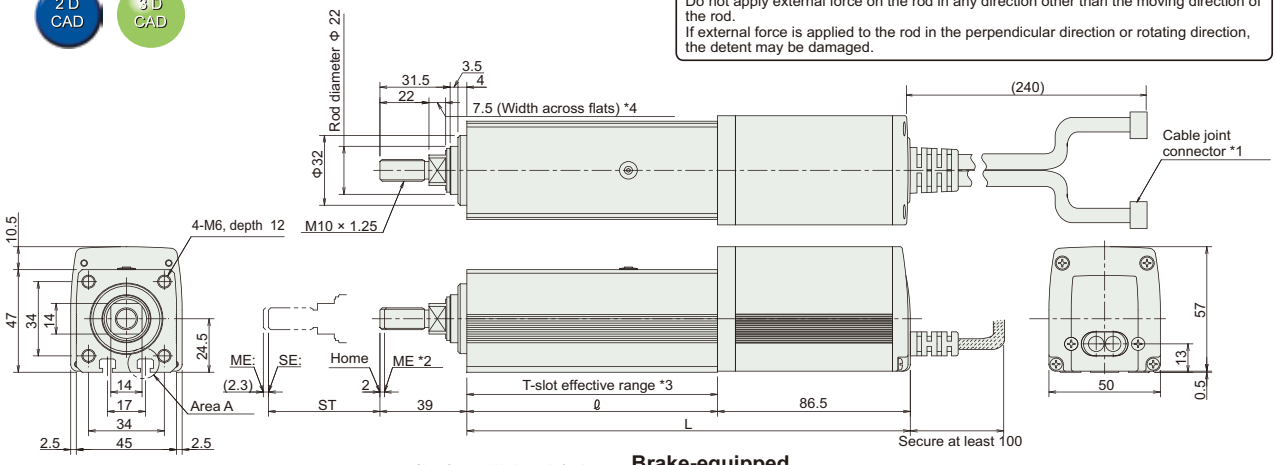
(1) As the stroke length increases, the maximum speed decreases due to hazardous ball screw RPMs. Check the maximum desired stroke speed in the Actuator Spec Table below.
(2) Because the RCP2 series uses a pulse motor, the load capacity decreases at high speeds. Refer to the Correlation Diagram of Speed and Load Capacity on page 29 and check the load capacity at the desired speed.
(3) The load capacity is based on operation at an acceleration of 0.2G. 0.2G is the upper limit of the acceleration. In addition, the horizontal load capacity assumes use of an external guide.
Please note that if external force is applied to the rod in a direction other than the proper direction the rod travels, the detent may get damaged.

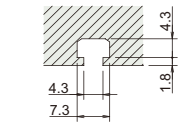
Dimensional Drawing

CAD data can be downloaded from IAI's website. www.intelligentactuator.com

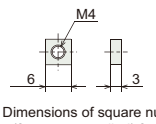
2D CAD 3D CAD

Caution
Do not apply external force on the rod in any direction other than the moving direction of the rod.
If external force is applied to the rod in the perpendicular direction or rotating direction, the detent may be damaged.

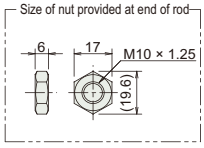




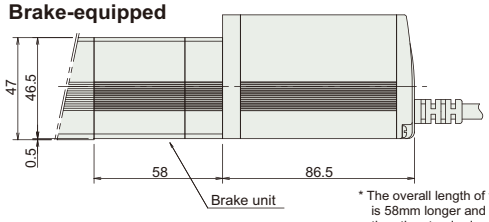
Detailed view of Area A



Dimensions of square nut (four nuts supplied) for mounting with T-slot



Brake-equipped



* The overall length of the brake-equipped model is 58mm longer and its weight is 0.4kg heavier than the standard model.

*1. Connect the motor-encoder cable.
*2. The rod will move to position ME after the actuator returns to the origin. Make sure that the slider will not interfere with any peripheral objects.
ME: Mechanical end; SE: Stroke end
* 3. Please note that there is no T-slot on the bottom of the brake unit.
*4. The orientation of the surface of the width across flats varies with each product. The dimensions in parentheses are reference values.

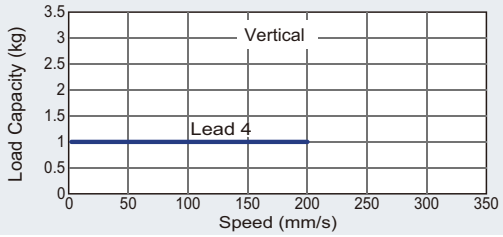
■ Dimensions and Weight by Stroke

Stroke	50	100	150	200	250	300
	112.5	162.5	212.5	262.5	312.5	362.5
L	199	249	299	349	399	449
Weight (kg)	1.35	1.6	1.85	2.1	2.35	2.6

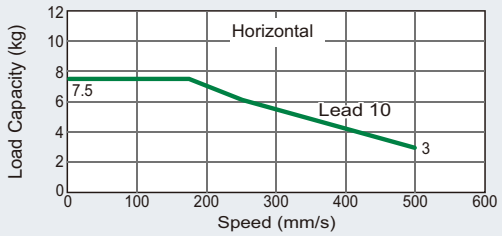
Correlation Diagram of Speed and Load Capacity

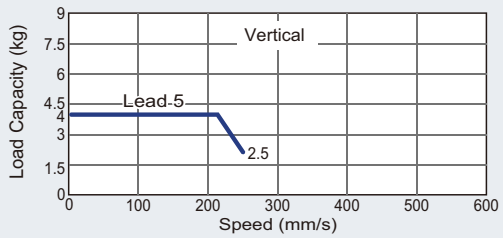
The load capacity decreases as the speed increases, due to the characteristics of the pulse motor used in the actuator.
Use the graph below to check if the desired speed and load capacity are satisfied.

RCP3-SA3C

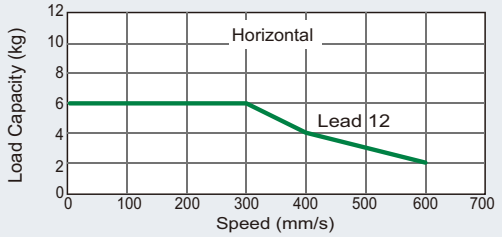


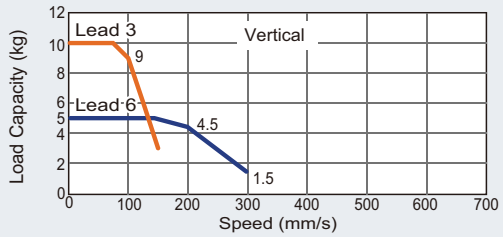
RCP3-SA4C



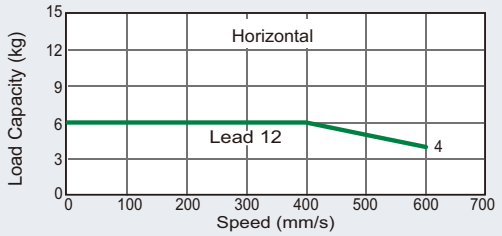


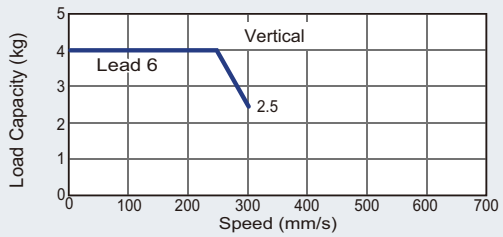
RCP3-SA5C



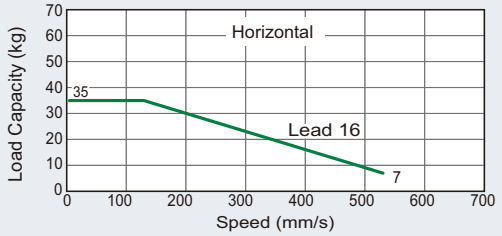


RCP2-SA5C

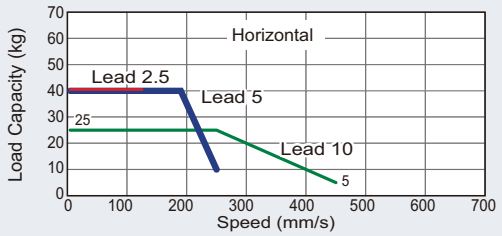


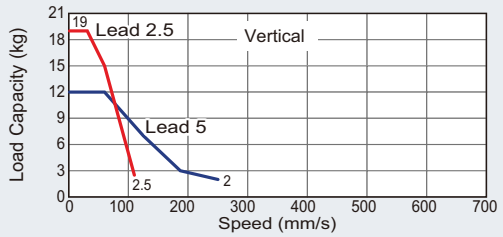


RCP2-SA7C



RCP2-RA4C





Type Description

Model numbers for each series of ROBO Cylinder consist of the following identifiers. For details, see the explanation below:
The range of selection for an identifier (e.g., lead, stroke) varies with each model. For details, refer to the description of each specific model.

Explanations of Identifiers

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller	Cable Length	Option
①	②	③	④	⑤	⑥	⑦	⑧	⑨

① Series	Indicates the name of the series.
② Type	Indicates the shape (e.g., the slider or rod type), material (e.g., aluminum or steel), size (e.g., 52mm wide), and motor coupling method of each model as shown below.

Type	Material/Guide	Body Width	Motor Coupling method
S (Slider) R (Rod)	A (Aluminum)	3 (Width: 30) 4 (Width: 40/42/45) 5 (Width: 52/54/55) 6 (Width: 58/64) 7 (Width: 60/68)	C (Coupling)

Example : SA5C
Shape : Slider
Material : Aluminum
Body Width: 52mm
Motor : Coupling specification

* Gripper and rotary are unique models.

③ Encoder Type	Indicates the type of encoder mounted to the actuator (absolute type or incremental type).
I: Incremental	The position data of the slider gets erased when the ROBO Cylinder is powered off. Therefore, homing is required each time the ROBO Cylinder is powered on.
④ Motor Type	Indicates the type of motor used in the actuator. Because the RCP3/RCP2 series uses a pulse motor, the motor type indicates the size of the motor (i.e., 20P for 20-□ motor).
⑤ Lead	Indicates the lead of the ball screw (i.e., the travel distance of the slider when the ball screw rotates once).
⑥ Stroke	Indicates the stroke (range of motion) of the actuator (in mm or degrees).
⑦ Applicable Controller (I/O type)	Indicates the type of controller that can be connected.
⑧ Cable Length	Indicates the length of motor-encoder cable that connects the actuator and the controller.
⑨ Options	Indicates the types of options attached to the actuator. * If you are selecting multiple options, specify them in alphabetical order (e.g., A3-B-FT).

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